# CANONICAL SUBRELATIONS OF ERGODIC EQUIVALENCE RELATIONS-SUBRELATIONS 

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#### Abstract

Given an ergodic measured discrete equivalence relation $\mathcal{R}$ and an ergodic subrelation $\mathcal{S} \subset \mathcal{R}$ of finite index, C. Sutherland showed that they are represented by the cross products $\mathcal{P} \rtimes_{\alpha} G$ and $\mathcal{P} \rtimes_{\alpha} H$ of an ergodic subrelation $\mathcal{P} \subset \mathcal{S}$ by a finite group outer action $\alpha_{G}$ and a subgroup action $\alpha_{H}$. This result is strengthened in the sense that the subgroup $H$ may be chosen so that it does not contain any non-trivial normal subgroup of $G$ and that the collection $\left\{\mathcal{P}, H \subset G, \alpha_{G}\right\}$ is invariant for the orbit equivalence of the pair of $\mathcal{R}$ and $\mathcal{S}$. In amenable case of type $\mathrm{II}_{1}$, a complete invariant for the orbit equivalence of pairs of an ergodic measured discrete equivalence relation and an ergodic subrelation of finite index is obtained.


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## 1. INTRODUCTION

Let $(X, \mathfrak{B}, m)$ be a Lebesgue space and $\mathcal{R} \subset X \times X$ be a measured discrete equivalence relation. So, each orbit $\mathcal{R}(x)=\{y \in X \mid(y, x) \in \mathcal{R}\}$ is a countable set a.e. $x$. It is known that every measured discrete equivalence relation $\mathcal{R}$ can be characterized to be a subset

$$
\mathcal{R}=\{(g x, x) \mid g \in \mathcal{G}, x \in X\}
$$

where $\mathcal{G}$ is a countable group of non-singular (invertible) transformations on $(X, \mathfrak{B}, m)$ (Feldman and Moore [2]). By $m_{l}$, we denote the measure on $\mathcal{R}$ defined by $\mathrm{d} m_{l}(y, x)=\mathrm{d} m(x),(y, x) \in \mathcal{R}$. A measurable subset $\mathcal{S}$ of the Lebesgue
space $\left(\mathcal{R}, m_{l}\right)$ is called a subrelation if it is an equivalence relation set. We say that pairs $\{\mathcal{R}, \mathcal{S}\}$ and $\left\{\mathcal{R}^{\prime}, \mathcal{S}^{\prime}\right\}$ of a measured discrete equivalence relation and a subrelation are orbit equivalence if there exists a measure isomorphism (i.e. a measurable, non-singular and invertible map) $\varphi$ satisfying

$$
\varphi(\mathcal{R}(x))=\mathcal{R}^{\prime}(\varphi x) \quad \text { and } \quad \varphi(\mathcal{S}(x))=\mathcal{S}^{\prime}(\varphi x) \quad \text { a.e. } x .
$$

We will show that given an ergodic measured discrete equivalence relation $\mathcal{R}$ and an ergodic subrelation $\mathcal{S}$ of finite index, there is a system of a subrelation $\mathcal{P} \subset \mathcal{S}$, a finite group $G$ and a subgroup $H \subset G$ and an action $g \in G \mapsto \alpha_{g} \in N[\mathcal{P}]$ such that
(i) $H$ does not contain any normal subgroup $\neq\{e\}$ of $G$,
(ii) $\alpha_{G}$ is outer,
(iii) $\mathcal{R}=\mathcal{P} \rtimes_{\alpha} G$ and $\mathcal{S}=\mathcal{P} \rtimes_{\alpha} H$;
where $N[\mathcal{P}]$ denotes the normalizer group of $\mathcal{P}$ (see Section 2). Moreover, the subrelation $\mathcal{P}$, the conjugacy class of the action $\alpha_{G}$ over $\mathcal{P}$ and the conjugacy class of the pair $\{G, H\}$ of a group and a subgroup satisfying the conditions (i)-(iii) are uniquely determined up to orbit equivalence of the pair $\{\mathcal{R}, \mathcal{S}\}$ (Theorem 4.1). So, we call this system the canonical system of the inclusion $\mathcal{R} \supset \mathcal{S}$. We note that the existence of $\left\{\mathcal{P}, H \subset G, \alpha_{G}\right\}$ satisfying the conditions (ii) and (iii) was shown by Sutherland ([10]).

The uniqueness of the canonical system will lead us to classifying the pairs of an amenable ergodic measured discrete equivalence relation and an ergodic subrelation of finite index. As a matter of fact, a generalization of Dye's theorem is obtained (Theorem 4.2). Namely, the conjugacy class of the pair $\{G, H\}$ of a finite group and a subgroup appearing in the canonical system is a complete invariant for the orbit equivalence in case of amenable relations of type $\mathrm{II}_{1}$. About type III case, the classification will be discussed elsewhere ([7]).

An idea to prove the main theorem (Theorem 4.1) is to develop a discrete decomposition theorem for an index cocycle. Namely, as shown in [3], the pair $\{\mathcal{R}, \mathcal{S}\}$ provides an index cocycle. It is known that if a cocycle is a Radon-Nikodym derivative then a type III relation is decomposed into a type $\mathrm{II}_{\infty}$ relation and a $\mathbb{Z}$ action satisfying a scaling-down property through a cross product. So, the problem is what an analogue of the discrete decomposition of the pair $\mathcal{R} \supset \mathcal{S}$ for an index cocycle is.

For this, we will introduce the index ratio set (Definition 2.4). This is the pair of a finite group and a subgroup, whose conjugacy class is invariant for the orbit equivalence. Then, roughly speaking, the subrelation $\mathcal{P}$ and the action $\alpha_{G}$
will be obtained in such a way that the type $\mathrm{I}_{\infty}$ relation and a $\mathbb{Z}$-action are obtained in the discrete decomposition of a type III relation using the Krieger's ratio set. The computation of an index ratio set will be described in the example of a measured discrete equivalence relation and an ergodic subrelation arising from a labeled graph (Section 5).

## 2. INDEX RATIO SET

Let $\mathcal{R} \supset \mathcal{S}$ be an ergodic measured discrete equivalence relation and an ergodic subrelation on $(X, \mathfrak{B}, m)$ (see [2]). We let

$$
\left.\begin{array}{l}
{[\mathcal{R}]=\{\psi \mid \psi \text { a mesurable, invertible, non-singular transformation such that }} \\
\quad \psi x \in \mathcal{R}(x) \text { a.e. } x\}, \\
{[\mathcal{R}]_{*}=\{\psi \mid \psi \text { an invertible, non-singular map from a measurable subset }} \\
\text { Dom }(\psi) \text { onto a measurable subset } \operatorname{Im}(\psi) \text { such that } \\
\psi x \in \mathcal{R}(x) \text { a.e. } x \in \operatorname{Dom} \psi\}, \text { and }
\end{array}\right] \begin{aligned}
& N[\mathcal{R}]=\{\psi \mid \psi \text { a measurable, invertible, non-singular transformation such } \\
& \text { that } \psi(\mathcal{R}(x))=\mathcal{R}(\psi(x)) \text { a.e. } x\} .
\end{aligned}
$$

We note that both $[\mathcal{R}]$ and $N[\mathcal{R}]$ are groups.
It is known from [3] that the function $x \in X \mapsto \#\{\mathcal{S}(y) \mid(y, x) \in \mathcal{R}\}$ is measurable and is a constant $\leqslant \infty$ a.e. $x$. By $[\mathcal{R}: \mathcal{S}]$, we denote this constant and call it the index of $\mathcal{S}$. The Jones index ([8]) of the Krieger factor and the subfactor constructed from the pair $\mathcal{R}$ and $\mathcal{S}$ is equal to $[\mathcal{R}: \mathcal{S}]$.

If $N=[\mathcal{R}: \mathcal{S}]<\infty$ then one can get the set of transformations $\varphi_{i}$ in $[\mathcal{R}]$, $i=0,1, \ldots, N-1$, such that $\varphi_{0}=$ id, and $\mathcal{R}(x)=\bigcup_{i=0}^{N-1} \mathcal{S}\left(\varphi_{i} x\right)$. These $\varphi_{i}$ are called choice functions ([3]). If $(x, y) \in \mathcal{R}$ and $0 \leqslant i \leqslant N-1$, then an integer $j$ is uniquely determined by $\left(\varphi_{i} y, \varphi_{j} x\right) \in \mathcal{S}$. Thus, we have the permutation $\sigma(x, y) \in \Sigma_{N}$ defined by $\sigma(x, y)(i)=j$. Here the $\Sigma_{N}$ means the set of all permutations on the $N$ objects. Obviously, $\sigma:(x, y) \in \mathcal{R} \mapsto \sigma(x, y) \in \Sigma_{N}$ is a homomorphism and is called the index cocycle of the pair $\mathcal{R}$ and $\mathcal{S}([3])$. We let $[\mathcal{R}: \mathcal{S}]=N<\infty$ and set

$$
\begin{aligned}
& \mathbf{r}_{0}(\mathcal{S})=\left\{\theta \in \Sigma_{N} \mid\right. \\
& \text { there exists for any measurable subset } E \text { of positive } \\
& \\
& \text { measure a partial transformation } \varphi \in[\mathcal{S}]_{*} \text { such that } \\
& \\
& \operatorname{Dom}(\varphi), \operatorname{Im}(\varphi) \subset E, \text { and } \sigma(\varphi x, x)=\theta, \forall x \in \operatorname{Dom}(\varphi)\} .
\end{aligned}
$$

Thus $\mathbf{r}_{0}(\mathcal{S})$ is a subgroup of $\Sigma_{N}$. By $\operatorname{Ker}(\sigma)$, we denote the subrelation $\{(x, y) \in \mathcal{R} \mid \sigma(x, y)=e\} \subset \mathcal{S}$.

Lemma 2.1. $\#\{\operatorname{Ker}(\sigma)$-ergodic components $\} \leqslant N$ !.
Proof. Consider the subrelation $\mathcal{Q}$ of $\mathcal{S}$ defined by

$$
\mathcal{Q}=\left\{(x, y) \in \mathcal{S} \mid \sigma(x, y) \in \mathbf{r}_{0}(\mathcal{S})\right\}
$$

Let us choose any finite partition $\left\{A_{\lambda} \mid \lambda \in \Lambda\right\}$ of $X$ consisting of $\mathcal{Q}$-invariant measurable subsets of positive measure. If $(x, y),(x, z) \in \mathcal{S}$ and if $x \in A_{\gamma}, y \in$ $A_{\lambda}, z \in A_{\mu}$ and if $\lambda \neq \mu$, then since $A_{\lambda}$ and $A_{\mu}$ are disjoint $\mathcal{Q}$-invariant sets, $\sigma(z, y) \neq e$. Hence $\sigma(y, x) \neq \sigma(z, x)$. This implies $\#(\Lambda) \leqslant \#\left(\Sigma_{N}\right)=N$ !. We will show that both of the partitions of $X$ by the $\mathcal{Q}$-ergodic components and by the $\operatorname{Ker}(\sigma)$-ergodic components respectively coincide with each other. For this let $\left\{A_{\lambda} \mid \lambda \in \Lambda\right\}$ be the finite partition consisting of all $\mathcal{Q}$-ergodic components.

Since $\operatorname{Ker}(\sigma) \subset \mathcal{Q}$, every $\mathcal{Q}$-invariant set is $\operatorname{Ker}(\sigma)$-invariant. We want to show that each $A_{\lambda}$ is a $\operatorname{Ker}(\sigma)$-ergodic component. For this we let $\lambda \in \Lambda$ and $E$ and $F$ be measurable subsets of $A_{\lambda}$ of positive measure. Since the restriction $\left.\mathcal{Q}\right|_{A_{\lambda}}$ of $\mathcal{Q}$ to the set $A_{\lambda}$ is ergodic, we obtain a $\varphi \in[\mathcal{Q}]_{*}$, and a $\theta \in \mathbf{r}_{0}(\mathcal{S})$ satisfying

$$
\operatorname{Dom}(\varphi) \subset E, \quad \operatorname{Im}(\varphi) \subset F \quad \text { and } \quad \sigma(\varphi x, x)=\theta, \quad \forall x \in \operatorname{Dom}(\varphi)
$$

By definition of $\mathbf{r}_{0}(\mathcal{S})$, there exists a $\psi \in[\mathcal{S}]_{*}$ satisfying

$$
\operatorname{Dom}(\psi), \operatorname{Im}(\psi) \subset \operatorname{Im}(\varphi) \quad \text { and } \quad \sigma(\psi x, x)=\theta^{-1}, \quad \forall x \in \operatorname{Dom}(\varphi)
$$

Then,

$$
\sigma(\psi \cdot \varphi x, x)=\sigma(\psi \cdot \varphi x, \varphi x) \sigma(\varphi x, x)=\theta^{-1} \theta=e, \quad \forall x \in \varphi^{-1}(\operatorname{Dom}(\psi))
$$

Hence $\psi \cdot \varphi \in[\operatorname{Ker}(\sigma)]_{*}, \operatorname{Dom}(\psi \cdot \varphi) \subset E$, and $\operatorname{Im}(\psi \cdot \varphi) \subset F$. On the other hand, since $\operatorname{Ker}(\sigma) \subset \mathcal{Q}$, the set $A_{\lambda}$ is a $\operatorname{Ker}(\sigma)$-invariant. Therefore $A_{\lambda}$ is a $\operatorname{Ker}(\sigma)$-ergodic component.

Throughout the rest of this section, we let $\left\{A_{\lambda} \mid \lambda \in \Lambda\right\}$ be the partition of $X$ consisting of all $\operatorname{Ker}(\sigma)$-ergodic components. Let $\lambda \in \Lambda$ and set

$$
\begin{gathered}
\mathbf{r}_{\lambda}(\mathcal{R})=\left\{\theta \in \Sigma_{N} \mid \text { there exists for any measurable subset } A \subset A_{\lambda}\right. \text { of positive } \\
\text { measure a } \varphi \in[\mathcal{R}]_{*} \operatorname{such} \text { that } \operatorname{Dom}(\varphi), \operatorname{Im}(\varphi) \subset A \text { and } \\
\sigma(\varphi x, x)=\theta, \forall x \in \operatorname{Dom}(\varphi)\} \\
\mathbf{r}_{\lambda}(\mathcal{S})=\left\{\theta \in \Sigma_{N} \mid \text { there exists for any measurable subset } A \subset A_{\lambda}\right. \text { of positive } \\
\text { measure a } \varphi \in[\mathcal{S}]_{*} \text { such that } \operatorname{Dom}(\varphi), \operatorname{Im} \varphi \subset A, \text { and } \\
\sigma(\varphi x, x)=\theta, \forall x \in \operatorname{Dom}(\varphi)\}
\end{gathered}
$$

Then both $\mathbf{r}_{\lambda}(\mathcal{R})$ and $\mathbf{r}_{\lambda}(\mathcal{S})$ are the subgroups of $\Sigma_{N}$.

Lemma 2.2. Let $\lambda \in \Lambda$. Then
(i) $\sigma(y, x) \in \mathbf{r}_{\lambda}(\mathcal{S})$, a.e. $(y, x) \in \mathcal{S}$ with $x, y \in A_{\lambda}$, and
(ii) $\sigma(y, x) \in \mathbf{r}_{\lambda}(\mathcal{R})$, a.e. $(y, x) \in \mathcal{R}$ with $x, y \in A_{\lambda}$.

Proof. (i) Let $\varphi \in[\mathcal{S}]_{*}$ be such that $\operatorname{Dom}(\varphi), \operatorname{Im}(\varphi) \subset A_{\lambda}$ and $\sigma(\varphi x, x)=$ a constant $=\theta, \forall x \in \operatorname{Dom}(\varphi)$. We show that $\theta \in \mathbf{r}_{\lambda}(\mathcal{S})$. Since the restriction $\left.\operatorname{Ker}(\sigma)\right|_{A_{\lambda}}$ is ergodic, there exist for every set $E \subset A_{\lambda}$ of positive measure, partial transformations $\psi_{i} \in[\mathcal{P}]_{*}, i=1,2$ satisfying that $\operatorname{Dom}\left(\psi_{1}\right) \subset E, \operatorname{Im} \psi_{1} \subset \operatorname{Dom}(\varphi)$ and $\operatorname{Dom}\left(\psi_{2}\right) \subset \operatorname{Im}\left(\varphi \cdot \psi_{1}\right), \operatorname{Im}\left(\psi_{2}\right) \subset E$. So, we see that $\operatorname{Dom}\left(\psi_{2} \cdot \varphi \cdot \psi_{1}\right), \operatorname{Im}\left(\psi_{2}\right.$. $\left.\varphi \cdot \psi_{1}\right) \subset E$ and that

$$
\begin{aligned}
\sigma\left(\psi_{2} \cdot \varphi \cdot \psi_{1} x, x\right) & =\sigma\left(\psi_{2} \cdot \varphi \cdot \psi_{1} x, \varphi \cdot \psi_{1} x\right) \sigma\left(\varphi \cdot \psi_{1} x, \psi_{1} x\right) \sigma\left(\psi_{1} x, x\right) \\
& =e \cdot \theta \cdot e=\theta
\end{aligned}
$$

$\forall x \in \operatorname{Dom}\left(\psi_{2} \cdot \varphi \cdot \psi_{1}\right) \subset E$. Since $\psi_{2} \cdot \varphi \cdot \psi_{1} \in[\mathcal{S}]_{*}$, we have $\theta \in \mathbf{r}_{\lambda}(\mathcal{S})$. The proof of (ii) is similarly done. So, we omit it.

Lemma 2.3. There exist permutations $\theta_{\lambda, \mu} \in \Sigma_{N}, \lambda, \mu \in \Lambda$ satisfying the following conditions:
(i) For a.e. $(y, x) \in \mathcal{R}$ with $y \in A_{\mu}$ and $x \in A_{\lambda},(y, x) \in \mathcal{S}$ if and only if $\sigma(y, x) \in \mathrm{r}_{\mu}(\mathcal{S}) \cdot \theta_{\mu, \lambda} ;$
(ii) $\theta_{\lambda, \mu} \cdot \theta_{\mu, \gamma}=\theta_{\lambda, \gamma}, \theta_{\lambda, \lambda}=e$;
(iii) $\theta_{\lambda, \mu} \cdot \mathbf{r}_{\mu}(\mathcal{S}) \cdot \theta_{\lambda, \mu}^{-1}=\mathbf{r}_{\lambda}(\mathcal{S}), \theta_{\lambda, \mu} \cdot \mathbf{r}_{\mu}(\mathcal{R}) \cdot \theta_{\lambda, \mu}^{-1}=\mathbf{r}_{\lambda}(\mathcal{R})$.

Proof. We choose and fix a $\lambda_{0}$ in $\Lambda$. Let $\lambda \in \Lambda$, then since $\mathcal{S}$ is ergodic there exists a partial transformation $\varphi \in[\mathcal{S}]_{*}$ such that $\operatorname{Dom}(\varphi) \subset A_{\lambda_{0}}, \operatorname{Im}(\varphi) \subset A_{\lambda}$, $\sigma(\varphi x, x)=$ a constant, $\forall x \in \operatorname{Dom}(\varphi)$, and such that $\varphi x=x, \forall x \in \operatorname{Dom}(\varphi)$, if $\lambda=\lambda_{0}$. By $\varphi_{\lambda}$ and $\theta_{\lambda, \lambda_{0}}$ we denote such a partial transformation $\varphi$ and the corresponding constant in $\Sigma_{N}$. If $\varphi^{\prime}$ is another choice of a partial transformation in $[\mathcal{S}]_{*}$ having the corresponding constant $\theta^{\prime}$, then since $\left.\operatorname{Ker}(\sigma)\right|_{A_{\lambda_{0}}}$ is ergodic, we obtain a partial transformation $\psi \in[\operatorname{Ker}(\sigma)]_{*}$ such that $\operatorname{Dom}(\psi) \subset \operatorname{Dom}\left(\varphi_{\lambda}\right)$, $\operatorname{Im}(\psi) \subset \operatorname{Dom}\left(\varphi^{\prime}\right)$. Then,

$$
\left.\varphi^{\prime} \cdot \psi \cdot \varphi_{\lambda}^{-1}\right|_{\varphi_{\lambda}(\operatorname{Dom}(\psi))} \in\left[\left.\mathcal{S}\right|_{A_{\lambda}}\right]_{*}
$$

and

$$
\sigma\left(\varphi^{\prime} \cdot \psi \cdot \varphi_{\lambda}^{-1} x, x\right)=\theta^{\prime} \cdot \theta_{\lambda, \lambda_{0}}^{-1}, \quad \forall x \in \varphi_{\lambda}(\operatorname{Dom}(\psi))
$$

So, by Lemma 2.2, we see $\theta^{\prime} \cdot \theta_{\lambda, \lambda_{0}}^{-1} \in \mathbf{r}_{\lambda}(\mathcal{S})$. Thus, $\sigma(y, x) \in \mathbf{r}_{\lambda}(\mathcal{S}) \cdot \theta_{\lambda, \lambda_{0}}$ for a.e. $(y, x) \in \mathcal{S}$ with $y \in A_{\lambda}$ and $x \in A_{\lambda_{0}}$. Similarly, we see that $\sigma(y, x) \in \mathbf{r}_{\lambda_{0}}(\mathcal{S}) \cdot \theta_{\lambda, \lambda_{0}}^{-1}$ for a.e. $(y, x) \in \mathcal{S}$ with $y \in A_{\lambda_{0}}$ and $x \in A_{\lambda}$.

Next if $h \in \mathbf{r}_{\lambda}(\mathcal{S})$ then we choose a partial transformation $\varphi \in[\mathcal{S}]_{*}$ such that

$$
\operatorname{Dom}(\varphi), \operatorname{Im}(\varphi) \subset \operatorname{Im}\left(\varphi_{\lambda}\right), \quad \sigma(\varphi x, x)=h, \quad \forall x \in \operatorname{Dom}(\varphi)
$$

So,

$$
\left.\varphi_{\lambda}^{-1} \cdot \varphi \cdot \varphi_{\lambda}\right|_{\varphi_{\lambda}^{-1}(\operatorname{Dom}(\psi))} \in\left[\left.\mathcal{S}\right|_{A_{\lambda_{0}}}\right]_{*},
$$

and

$$
\sigma\left(\varphi_{\lambda}^{-1} \cdot \varphi \cdot \varphi_{\lambda} x, x\right)=\theta_{\lambda, \lambda_{0}}^{-1} \cdot h \cdot \theta_{\lambda, \lambda_{0}}, \quad \forall x \in \varphi_{\lambda}^{-1}(\operatorname{Dom}(\varphi))
$$

By Lemma 2.2, $\theta_{\lambda, \lambda_{0}}^{-1} h \theta_{\lambda, \lambda_{0}} \in \mathbf{r}_{\lambda_{0}}(\mathcal{S})$. Thus, $\theta_{\lambda, \lambda_{0}}^{-1} \cdot \mathbf{r}_{\lambda}(\mathcal{S}) \cdot \theta_{\lambda, \lambda_{0}} \subset \mathbf{r}_{\lambda_{0}}(\mathcal{S})$. Similarly we see that if $h \in \mathbf{r}_{\lambda}(\mathcal{R})$, then $\theta_{\lambda, \lambda_{0}}^{-1} h \theta_{\lambda, \lambda_{0}} \in \mathbf{r}_{\lambda_{0}}(\mathcal{R})$ and that $\theta_{\lambda, \lambda_{0}}^{-1} \cdot \mathbf{r}_{\lambda}(\mathcal{R}) \cdot \theta_{\lambda, \lambda_{0}} \subset$ $\mathbf{r}_{\lambda_{0}}(\mathcal{R})$.

Replacing $\lambda_{0}$ by $\lambda$ in the above argument, we see $\theta_{\lambda, \lambda_{0}} \cdot \mathbf{r}_{\lambda_{0}}(\mathcal{S}) \cdot \theta_{\lambda, \lambda_{0}}^{-1} \subset \mathbf{r}_{\lambda}(\mathcal{S})$ and $\theta_{\lambda, \lambda_{0}} \cdot \mathbf{r}_{\lambda_{0}}(\mathcal{R}) \cdot \theta_{\lambda, \lambda_{0}}^{-1} \subset \mathbf{r}_{\lambda}(\mathcal{R})$.

We define

$$
\theta_{\lambda_{0}, \lambda}=\theta_{\lambda, \lambda_{0}}^{-1}, \quad \theta_{\lambda, \mu}=\theta_{\lambda, \lambda_{0}} \cdot \theta_{\lambda_{0}, \mu}, \quad \lambda, \mu \in \Lambda
$$

Then,

$$
\begin{aligned}
& \theta_{\lambda, \mu} \cdot \mathbf{r}_{\mu}(\mathcal{S}) \cdot \theta_{\lambda, \mu}^{-1}=\mathbf{r}_{\lambda}(\mathcal{S}), \quad \theta_{\lambda, \mu} \cdot \mathbf{r}_{\mu}(\mathcal{R}) \cdot \theta_{\lambda, \mu}^{-1}=\mathrm{r}_{\lambda}(\mathcal{R}), \\
& \sigma(y, x) \in \mathbf{r}_{\mu}(\mathcal{S}) \cdot \theta_{\mu, \lambda} \quad \text { a.e. }(y, x) \in \mathcal{S} \text { with } y \in A_{\mu}, x \in A_{\lambda} .
\end{aligned}
$$

Finally, we will show that for a.e. $(y, x) \in \mathcal{R}$ with $y \in A_{\mu}$ and $x \in A_{\lambda},(y, x)$ is in $\mathcal{S}$ if $\sigma(y, x) \in \mathbf{r}_{\mu}(\mathcal{S}) \cdot \theta_{\mu, \lambda}$. To see this, let $\lambda, \mu \in \Lambda, \varphi \in[\mathcal{R}]_{*}$ and $h \in \mathbf{r}_{\mu}(\mathcal{S})$ be such that

$$
\operatorname{Dom}(\varphi) \subset A_{\lambda}, \quad \operatorname{Im}(\varphi) \subset A_{\mu}, \quad \sigma(\varphi x, x)=h \theta_{\mu, \lambda}, \quad \forall x \in \operatorname{Dom}(\varphi)
$$

Since $\left.\operatorname{Ker}(\sigma)\right|_{A_{\mu}}$ is ergodic, we get a partial transformation $\psi \in[\mathcal{S}]_{*}$ such that

$$
\operatorname{Dom}(\psi) \subset \operatorname{Im}(\varphi), \quad \operatorname{Im}(\psi) \subset \operatorname{Im}\left(\varphi_{\mu}\right), \quad \sigma(\psi x, x)=h^{-1}, \quad \forall x \in \operatorname{Dom}(\psi)
$$

Similarly, we have a partial transformation $\psi^{\prime} \in\left[\left.\operatorname{Ker}(\sigma)\right|_{A_{\lambda_{0}}}\right]_{*}$ such that

$$
\operatorname{Dom}\left(\psi^{\prime}\right) \subset \operatorname{Im}\left(\varphi_{\mu}^{-1}(\operatorname{Im}(\psi))\right), \quad \operatorname{Im}\left(\psi^{\prime}\right) \subset \operatorname{Dom}\left(\varphi_{\lambda}\right)
$$

Then, by setting $\psi^{\prime \prime}=\varphi_{\lambda} \cdot \psi^{\prime} \cdot \varphi_{\mu}^{-1} \cdot \psi \cdot \varphi \in[\mathcal{R}]_{*}$, we have $\sigma\left(\psi^{\prime \prime} x, x\right)=e, \forall x \in$ $\operatorname{Dom}\left(\psi^{\prime \prime}\right) \subset A_{\lambda}$, so that $\psi^{\prime \prime} \in\left[\left.\operatorname{Ker}(\sigma)\right|_{A_{\lambda}}\right]_{*}$. Thus, $\varphi=\psi^{-1} \cdot \varphi_{\mu} \cdot \psi^{\prime-1} \cdot \varphi_{\lambda}^{-1} \cdot \psi^{\prime \prime-1} \in$ $[\mathcal{S}]_{*}$.

By Lemma 2.3, the conjugacy class of the group $\mathbf{r}_{\lambda}(\mathcal{R})$ and the subgroup $\mathbf{r}_{\lambda}(\mathcal{S})$ does not depend on a choice of $\lambda \in \Lambda$. So, we have

Definition 2.4. We call the conjugacy class of the pair of the finite group $\mathbf{r}_{\lambda}(\mathcal{R})$ and the subgroup $\mathbf{r}_{\lambda}(\mathcal{S})$ the index ratio set and denote it by $\{\mathbf{r}(\mathcal{R}), \mathbf{r}(\mathcal{S})\}$.

Lemma 2.5. The pair of the index ratio sets $\mathbf{r}(\mathcal{R})$ and $\mathbf{r}(\mathcal{S})$ does not depend on a choice of the set of choice functions $\left\{\varphi_{i}\right\}_{0 \leqslant i \leqslant N-1}$ and in fact depends only on the orbit equivalence class of $\mathcal{R}$ and $\mathcal{S}$.

Proof. If $\sigma^{\prime}$ is the index cocycle determined by another set of choice functions $\varphi_{i}^{\prime}$ of $\mathcal{S} \subset \mathcal{R}$, then $\sigma$ and $\sigma^{\prime}$ are cohomologous ([3]), that is, there exists a measurable function $x \in X \mapsto v(x) \in \Sigma_{N}$ such that

$$
\sigma^{\prime}(x, y)=v(x) \sigma(x, y) v(y)^{-1}, \quad(x, y) \in \mathcal{R} .
$$

Let $\lambda_{0} \in \Lambda$ and let $\left\{B_{i} \mid i \in I\right\}$ be the finite partition of $X$ consisting of all $\operatorname{Ker}\left(\sigma^{\prime}\right)$-ergodic components. Let $i \in I$ be such that $m\left(A_{\lambda_{0}} \cap B_{i}\right)>0$, then we have a $\gamma$ in $\Sigma_{N}$ such that $m\left(\{x \in X \mid v(x)=\gamma\} \cap A_{\lambda_{0}} \cap B_{i}\right)>0$. Applying Lemma 2.2, we see that except on a null set, the range of $\sigma$ and $\sigma^{\prime}$ of the restriction of $\mathcal{S}$ to this intersection coincide with $\mathbf{r}_{\lambda_{0}}(\mathcal{S})$ and $\mathbf{r}_{i}(\mathcal{S})$ respectively. So, we have $\mathbf{r}_{i}(\mathcal{S})=\gamma \cdot \mathbf{r}_{\lambda_{0}}(\mathcal{S}) \cdot \gamma^{-1}$. Similarly we have $\mathbf{r}_{i}(\mathcal{R})=\gamma \cdot \mathbf{r}_{\lambda_{0}}(\mathcal{R}) \cdot \gamma^{-1}$.

We let $\widetilde{\mathcal{R}}$ be the measured discrete equivalence relation on $\left(X \times \mathbb{R}, m \times e^{u} \mathrm{~d} u\right)$ defined by

$$
((x, u),(y, v)) \in \widetilde{\mathcal{R}}
$$

if $(x, y) \in \mathcal{R}$ and $v=u-\log \delta(y, x)$, where $(x, u),(y, v) \in X \times \mathbb{R}$. Here $\delta(x, y)$ means the Radon-Nikodym derivative. Then $\widetilde{\mathcal{R}}$ is of type $\mathrm{I}_{\infty}$. By $X^{\mathcal{R}}$ we denote the quotient space of $X \times \mathbb{R}$ by the measurable partition consisting of all ergodic components of $\widetilde{\mathcal{R}}$. We let $\pi^{\mathcal{R}}$ be the natural surjection from $X \times \mathbb{R}$ to $X^{\mathcal{R}}$. By $\left\{T_{t} \mid t \in \mathbb{R}\right\}$, we denote the flow $T_{t}(x, u)=(x, u+t)$ for $(x, u) \in X \times \mathbb{R}, t \in \mathbb{R}$. By $\left\{F_{t}^{\mathcal{R}} \mid t \in \mathbb{R}\right\}$, we denote the factor flow of $\left\{T_{t} \mid t \in \mathbb{R}\right\}$ to the quotient space $X^{\mathcal{R}}$ through the factor map $\pi^{\mathcal{R}}$, that is, $\pi^{\mathcal{R}} T_{t}=F_{t}^{\mathcal{R}} \pi^{\mathcal{R}}, \forall t \in \mathbb{R}$. The flow $\left\{F_{t}^{\mathcal{R}} \mid t \in \mathbb{R}\right\}$ is called the associated flow of $\mathcal{R}$ ([4]) and simply denoted by $F^{\mathcal{R}}$.

It is known that $\mathcal{R}$ is ergodic and of type II if and only if $F^{\mathcal{R}}$ is the translation $u \in \mathbb{R} \mapsto u+t \in \mathbb{R}, t \in \mathbb{R}([4])$.

Lemma 2.6. (i) $\mathcal{R}$ is of type $\mathrm{II}_{1}$ if and ouly if $\mathcal{S}$ is of type $\mathrm{II}_{1}$.
(ii) $\mathcal{R}$ is of type $\mathrm{II}_{\infty}$ if and ouly if $\mathcal{S}$ is of type $\mathrm{II}_{\infty}$.

Proof. For almost all $\widetilde{\mathcal{S}}$-ergodic component there exists a uniquely determined $\widetilde{\mathcal{R}}$-ergodic component containing it. By $\pi_{\mathcal{R}}^{\mathcal{S}}$, we denote this map. Then,

$$
\pi_{\mathcal{R}}^{\mathcal{S}} F_{t}^{\mathcal{S}}=F_{t}^{\mathcal{R}} \pi_{\mathcal{R}}^{\mathcal{R}}, \quad \forall t \in \mathbb{R}
$$

The number of $\widetilde{\mathcal{S}}$-ergodic components contained in the $\widetilde{\mathcal{R}}$-ergodic component containing a point $(x, u)$ is at most $N$ a.e. $(x, u)$. Since $\pi_{\mathcal{R}}^{\mathcal{S}}$ is a finite to 1 factor map, the flow $F^{\mathcal{R}}$ is the translation if and only if so is $F^{\mathcal{S}}$, that is, $\mathcal{R}$ is of type II if and only if so is $\mathcal{S}$. In this case let $\mu$ be an invariant measure for $\mathcal{S}$. Then the uniqueness of invariant measure (up to constant) implies that $\mu$ is $\mathcal{R}$-invariant, too.

From now on in this section, we denote by $G$ and $H \subset G$ the finite group $\mathbf{r}_{\lambda_{0}}(\mathcal{R})$ and the subgroup $\mathbf{r}_{\lambda_{0}}(\mathcal{S})$. By $\left\{A_{\lambda} \mid \lambda \in \Lambda\right\}$, we denote the finite partition of $X$ consisting of all $\operatorname{Ker}(\sigma)$-ergodic components.

Lemma 2.7. There exists an action $g \in G \mapsto \alpha_{g} \in[\mathcal{R}] \cap N[\operatorname{Ker}(\sigma)]$ satisfying the following conditions:
(i) $\alpha_{G}$ is outer over $\operatorname{Ker}(\sigma)$, that is, if $\alpha_{g} \in[\operatorname{Ker}(\sigma)]$ then $g=e$;
(ii) $\alpha_{h} \in[\mathcal{S}], \forall h \in H$;
(iii) $\sigma\left(\alpha_{g} x, x\right)=\theta_{\lambda, \lambda_{0}} g \theta_{\lambda_{0}, \lambda}, \forall x \in A_{\lambda}, \forall \lambda \in \Lambda$;
(iv) $\alpha_{g}\left(A_{\lambda}\right)=A_{\lambda}, \forall g \in A_{\lambda}, \forall \lambda \in \Lambda$.

Proof. It is enough to construct such an action $\alpha_{G}$ on each $\operatorname{Ker}(\sigma)$-ergodic component. Let us first assume that $\mathcal{R}$ is of type $\mathrm{II}_{1}$, and let $\lambda \in \Lambda$.

We choose a subset $E_{\lambda} \subset A_{\lambda}$ with $m\left(E_{\lambda}\right)=\frac{m\left(A_{\lambda}\right)}{\#(G)}$. The ergodicity of $\left.\operatorname{Ker}(\sigma)\right|_{A_{\lambda}}$ allows us to get partial transformations $\eta_{g} \in\left[\left.\mathcal{R}\right|_{A_{\lambda}}\right]_{*}, g \in G$, such that

$$
\eta_{e}=\left.\mathrm{id}\right|_{E_{\lambda}}, \quad \operatorname{Dom}\left(\eta_{g}\right)=E_{\lambda}, \quad \sigma\left(\eta_{g} x, x\right)=\theta_{\lambda, \lambda_{0}} g \theta_{\lambda_{0}, \lambda}, \quad \text { a.e. } x \in E_{\lambda} .
$$

By (i) of Lemma 2.3, if $g \in H$ then $\eta_{g} \in\left[\left.\mathcal{S}\right|_{A_{\lambda}}\right]_{*}$.
We choose a finite partition $\left\{K_{g} \mid g \in G\right\}$ of $A_{\lambda}$ with $m\left(K_{g}\right)=\frac{m\left(A_{\lambda}\right)}{\#(G)}, g \in G$. Since $\operatorname{Im}\left(\eta_{g}\right)$ and $K_{g}$ are $\operatorname{Ker}(\sigma)$-Hopf equivalent, there exists a $v_{g}$ in $\left[\left.\operatorname{Ker}(\sigma)\right|_{A_{\lambda}}\right]_{*}$ such that $\operatorname{Dom}\left(v_{g}\right)=K_{g}, \operatorname{Im}\left(v_{g}\right)=\operatorname{Im}\left(\eta_{g}\right)$.

We define the transformation $\alpha_{f}, f \in G$, on each $A_{\lambda}$ by

$$
\alpha_{f} x=v_{f g}^{-1} \cdot \eta_{f g} \cdot \eta_{g}^{-1} \cdot v_{g} x, \quad x \in K_{g}, g \in G
$$

Then, obviously $\alpha_{f} \in[\mathcal{R}]$ and (iv) is satisfied.

To see (ii) and (iii),

$$
\begin{aligned}
\sigma\left(\alpha_{f} x, x\right)= & \sigma\left(\alpha_{f} x, \eta_{f g} \cdot \eta_{g}^{-1} \cdot v_{g} x\right) \sigma\left(\eta_{f g} \cdot \eta_{g}^{-1} \cdot v_{g} x, \eta_{g}^{-1} \cdot v_{g} x\right) \\
& \cdot \sigma\left(\eta_{g}^{-1} v_{g} x, v_{g} x\right) \sigma\left(v_{g} x, x\right) \\
= & e \cdot \theta_{\lambda, \lambda_{0}} f g \theta_{\lambda, \lambda_{0}}^{-1} \cdot \theta_{\lambda, \lambda_{0}} g^{-1} \cdot \theta_{\lambda, \lambda_{0}}^{-1} \cdot e=\theta_{\lambda, \lambda_{0}} f \theta_{\lambda, \lambda_{0}}, \quad x \in K_{g} .
\end{aligned}
$$

In particular, if $f \in H$, then $\sigma\left(\alpha_{f} x, x\right) \in \mathbf{r}_{\lambda}(\mathcal{S})$, and hence by Lemma 2.3, $\alpha_{f} \in[\mathcal{S}]$.

Finally, let us check that $\alpha_{G}$ is an outer action of $\operatorname{Ker}(\sigma)$. If $(x, y) \in \operatorname{Ker}(\sigma)$ and if $(x, y) \in A_{\lambda}$ then for all $g \in G$

$$
\sigma\left(\alpha_{g} x, \alpha_{g} y\right)=\sigma\left(\alpha_{g} x, x\right) \sigma(x, y) \sigma\left(y, \alpha_{g} y\right)=\theta_{\lambda, \lambda_{0}} g \theta_{\lambda_{0}, \lambda} \cdot e \cdot \theta_{\lambda, \lambda_{0}} g^{-1} \theta_{\lambda_{0}, \lambda}=e
$$

Thus, $\alpha_{g} \in N[\operatorname{Ker}(\sigma)]$. Let $g \in G$ be such that for some set $E$ of positive measure, $\left(\alpha_{g} x, x\right) \in \operatorname{Ker}(\sigma), \forall x \in E$, then since $\sigma\left(\alpha_{g} x, x\right)=\theta_{\lambda_{, ~} \lambda_{0}} g \theta_{\lambda_{0}, \lambda}, \forall x \in E$, we see that $g=e$.

In the case that $\mathcal{R}$ is of type $\mathrm{II}_{\infty}$, if $m\left(A_{\lambda}\right)=\infty$ then we replace the requirement $m\left(E_{\lambda}\right)=\frac{m\left(A_{\lambda}\right)}{\#(G)}$ in the above sequel by $m\left(E_{\lambda}\right)=\infty$ and $m\left(K_{g}\right)=\frac{m\left(A_{\lambda}\right)}{\#(G)}$ by $m\left(K_{g}\right)=\infty, \forall g \in G$ respectively. Then the proof is done by the similar argument. In the case that $\mathcal{R}$ is of type III, so is $\operatorname{Ker}(\sigma)$ by Lemma 2.6. In this case we do not need the requirement $m\left(K_{g}\right)=\frac{m\left(A_{\lambda}\right)}{\#(G)}$ anymore.

Definition 2.8. For a measured discrete equivalence relation $\mathcal{T}$ and an action $\gamma \in \Gamma \mapsto \beta_{\gamma} \in N[\mathcal{T}]$ of a countable group $\Gamma$, the relation $\mathcal{U}$ defined by

$$
(x, y) \in \mathcal{U} \quad \text { if } \quad y \in \bigcup_{\gamma \in \Gamma} \mathcal{T}\left(\beta_{\gamma} x\right)
$$

is called the cross product of $\mathcal{T}$ by $\beta_{\Gamma}$, and denote it by $\mathcal{T} \rtimes_{\beta} \Gamma$.
We notice that the action $\alpha_{G}$ in Lemma 2.7 is free, that is, if $g \in G$ is not $e$ then $\alpha_{g} x \neq x$ a.e. $x$. So, it allows us to get a Rholin set for the action $\alpha_{G}$. Namely, there exists for each $\lambda \in \Lambda$ a measurable set $F_{\lambda} \subset A_{\lambda}$ such that

$$
A_{\lambda}=\bigcup_{\lambda \in \Lambda} \alpha_{g}\left(F_{\lambda}\right) \quad \text { (disjoint union). }
$$

In the sequel of this section we will fix the subsets $F_{\lambda} \in \Lambda, \lambda \in \Lambda$.

Lemma 2.9. Let $\lambda \in \Lambda$. Then,

$$
\left.\operatorname{Ker}(\sigma)\right|_{A_{\lambda}} \rtimes_{\alpha} G=\left.\mathcal{R}\right|_{A_{\lambda}} \quad \text { and }\left.\quad \operatorname{Ker}(\sigma)\right|_{A_{\lambda}} \rtimes_{\alpha} H=\left.\mathcal{S}\right|_{A_{\lambda}}
$$

Proof. If $\lambda \in \Lambda,(x, y) \in \mathcal{R}$ and $x, y \in A_{\lambda}$, then

$$
\sigma\left(\alpha_{\sigma(y, x)} x, y\right)=\sigma\left(\alpha_{\sigma(y, x)} x, x\right) \sigma(x, y) \stackrel{\text { Lemma 2.7(iii) }}{=} \sigma(y, x) \sigma(x, y)=e .
$$

Hence,

$$
y \in \operatorname{Ker}(\sigma)\left(\alpha_{\sigma(y, x)} x\right)=\alpha_{\sigma(y, x)}(\operatorname{Ker}(\sigma)(x))
$$

Thus, $y \in\left(\left.\operatorname{Ker}(\sigma)\right|_{A_{\lambda}} \rtimes_{\alpha} G\right)(x)$, if $(x, y) \in \mathcal{R}$ with $x, y \in A_{\lambda}$ and $y \in\left(\left.\operatorname{Ker}(\sigma)\right|_{A_{\lambda}} \rtimes_{\alpha}\right.$ $H)(x)$, if $(x, y) \in \mathcal{S}$ with $x, y \in A_{\lambda}$.

We took the partial transformations $\varphi_{\lambda}, \lambda \in \Lambda$ in the proof of Lemma 2.3. Since $\left.\operatorname{Ker}(\sigma)\right|_{A_{\lambda_{0}}}$ is ergodic, we may and do assume that these have the same domain. So, we define the partial transformations $\psi_{\mu, \lambda}$ in $[\mathcal{S}]_{*}$ by

$$
\begin{aligned}
\psi_{\lambda, \lambda_{0}} & =\varphi_{\lambda} \\
\psi_{\lambda_{0}, \lambda} & =\varphi_{\lambda}^{-1} \\
\psi_{\lambda, \mu} & =\psi_{\lambda, \lambda_{0}} \psi_{\lambda_{0}, \mu}, \quad \lambda, \mu \in \Lambda .
\end{aligned}
$$

Definition 2.10. We define the subrelation $\mathcal{P}$ of $\mathcal{S}$ as follows: Let $x \in A_{\mu}$, $y \in A_{\lambda}$, where $\lambda, \mu \in \Lambda$. Then $(x, y) \in \mathcal{P}$ if either $\mu=\lambda$ and $(x, y) \in \operatorname{Ker}(\sigma)$, or, $\mu \neq \lambda$ and $(u, y),\left(x, \psi_{\mu, \lambda} u\right) \in \operatorname{Ker}(\sigma)$ for some $u \in A_{\lambda}$.

Theorem 2.11. The equivalence relation $\mathcal{P}$ is ergodic, and the system $\{\mathcal{P}$, $\left.H \subset G, \alpha_{G}\right\}$ in Lemma 2.7 satisfies the following properties:
(i) $G$ is a finite group and $H$ is a subgroup which does not include any normal subgroup $\neq\{e\}$ of $G$;
(ii) The action $\alpha_{G} \subset N[\mathcal{P}]$ is outer;
(iii) $\mathcal{R}=\mathcal{P} \rtimes_{\alpha} G, \mathcal{S}=\mathcal{P} \rtimes_{\alpha} H$.

We notice that the collection $\left\{\mathcal{P}, H \subset G, \alpha_{G}\right\}$ satisfying the conditions (ii) and (iii) was obtained by C. Sutherland ([10]). It will be made clear in the next section that the condition (i) in this theorem is a key for proving the uniqueness of $\left\{\mathcal{P}, H \subset G, \alpha_{G}\right\}$.

Proof. Each restriction $\left.\mathcal{P}\right|_{A_{\lambda}}=\left.\operatorname{Ker}(\sigma)\right|_{A_{\lambda}}$, is ergodic. For each $\lambda$ and $\mu \in \Lambda$ the partial transformation $\psi_{\mu, \lambda}$ in $[\mathcal{P}]_{*}$ hits the set $A_{\mu}$ from its domain in $A_{\lambda}$. So, $\mathcal{P}$ is ergodic.

We will show (ii). In order to see $\alpha_{G} \subset N[\mathcal{P}]$, we let $\mu, \lambda \in \Lambda$ and $g \in G$. Since both of the restrictions of $\operatorname{Ker}(\sigma)$ to the sets $A_{\lambda}$ and $A_{\mu}$ are ergodic, one can get for a.e. $(x, y) \in \mathcal{P}$ with $x \in A_{\lambda}$ and $y \in A_{\mu}$, points $u$ and $z \in \operatorname{Dom}\left(\psi_{\mu, \lambda}\right)$ satisfying

$$
(x, u) \in \operatorname{Ker}(\sigma), \quad\left(\psi_{\mu, \lambda} u, y\right) \in \operatorname{Ker}(\sigma) \quad \text { and } \quad\left(\alpha_{g} u, z\right) \in \operatorname{Ker}(\sigma)
$$

Then,

$$
\begin{aligned}
\sigma\left(\psi_{\mu, \lambda} z, \alpha_{g} y\right) & =\sigma\left(\psi_{\mu, \lambda} z, z\right) \sigma\left(z, \alpha_{g} u\right) \sigma\left(\alpha_{g} u, u\right) \sigma\left(u, \psi_{\mu, \lambda} u\right) \sigma\left(\psi_{\mu, \lambda} u, y\right) \sigma\left(y, \alpha_{g} y\right) \\
& =\theta_{\mu, \lambda} \cdot e \cdot \theta_{\lambda, \lambda_{0}} g \theta_{\lambda_{0}, \lambda} \cdot \theta_{\lambda, \mu} \cdot e \cdot \theta_{\mu, \lambda_{0}} g^{-1} \theta_{\lambda_{0}, \mu}=e
\end{aligned}
$$

Hence, $\left(\psi_{\mu, \lambda} z, \alpha_{g} y\right) \in \operatorname{Ker}(\sigma)$. On the other hand, $\left(\alpha_{g} x, \alpha_{g} u\right) \in \operatorname{Ker}(\sigma)$. Thus $\left(\alpha_{g} x, \alpha_{g} y\right) \in \mathcal{P}$. To see that $\alpha_{G}$ is outer, we let $E \subset X$ be of positive measure and $g \in G$ be such that $\alpha_{g} x \in \mathcal{P}(x), x \in E$. Since $x$ and $\alpha_{g} x$ sit on the same $\operatorname{Ker}(\sigma)$-ergodic component, and since the restriction of $\mathcal{P}$ to this set is just the same as the restriction of $\operatorname{Ker}(\sigma)$, we see that $\alpha_{g} x \in \operatorname{Ker}(\sigma)(x), x \in E$. Hence,

$$
\theta_{\lambda, \lambda_{0}} g \theta_{\lambda_{0}, \lambda}=\sigma\left(\alpha_{g} x, x\right)=e .
$$

Thus, $g=e$.
Next we will show (iii). We get for a.e. $(x, y) \in \mathcal{S}$ (respectively $(x, y) \in \mathcal{R}$ ) with $x \in A_{\lambda}$ and $y \in A_{\mu}$, a point $u$ in $\operatorname{Dom}\left(\psi_{\mu, \lambda}\right)$ such that $(u, x) \in \operatorname{Ker}(\sigma)$. Since $\left(y, \psi_{\mu, \lambda} u\right) \in \mathcal{S}$ (respectively $\left.\left(y, \psi_{\mu, \lambda} u\right) \in \mathcal{R}\right)$, it follows from Lemma 2.9 that

$$
\begin{aligned}
\left(\left.\operatorname{Ker}(\sigma)\right|_{A_{\mu}} \rtimes_{\alpha} H\right)\left(\psi_{\mu, \lambda} u\right) & \subset\left(\mathcal{P} \rtimes_{\alpha} H\right)(u)
\end{aligned}=\left(\mathcal{P} \rtimes_{\alpha} H\right)(x) .
$$

Thus, $y \in\left(\mathcal{P} \rtimes_{\alpha} H\right)(x)$ (respectively $\left.y \in\left(\mathcal{P} \rtimes_{\alpha} G\right)(x)\right)$.
Finally, we will show (i). Let $K$ be a normal subgroup of $G$ such that $K \subset H$. Let $G / K$ be the quotient group of $G$ by the subgroup $K$ and denote each coset $g K(=K g)$ by $[g]$, for $g \in G$. We choose and fix representatives $g_{j} \in G, j \in J$, so that $G / K=\left\{\left[g_{j}\right] \mid j \in J\right\}$.

Consider the coset space $G / H$ of $G$ by the subgroup $H$, that is, $g$ and $g^{\prime} \in G$ are equivalent if $g g^{\prime-1} \in H$ and we denote for $g \in G$ its equivalence class by $[g]_{H}$. Then there exist a subset $I \subset J$ such that

$$
\begin{aligned}
& \#(I)=\#(G / H) \\
& G / H=\left\{\left[g_{i}\right]_{H} \mid i \in I\right\} .
\end{aligned}
$$

In order to see this, we notice that if an element $g$ in $G$ satisfies $[g]=[h]$ for some $h \in H$ then $g \in H$. So, we may set

$$
H_{K}=\{[g] \in G / K \mid g \in H\}
$$

Obviously, $H_{K}$ is a subgroup of $G / K$. So, consider the coset space of $G / K$ by $H_{K}$ defined by that if $[g]$ and $[f] \in G / K$ then $[g]$ is equivalent with $[f]$ if $[g][f]^{-1} \in$ $H_{K}$. Then we see that the above equivalence relation is just the same as the equivalence $[g]_{H}=[f]_{H}$. Hence, we get a subset $I \subset J$ with $\#(I)=\#(G / H)$ so that $\left[g_{i}\right]_{H}, i \in I$, are all equivalence classes of $G / H$.

We see that $\left\{\alpha_{g_{i}} \mid i \in I\right\}$ is the set of choice functions of $\mathcal{S} \subset \mathcal{R}$. In fact, $\left\{\alpha_{g_{i}} \mid i \in I\right\}$ satisfies

$$
\bigcup_{i \in I} \mathcal{S}\left(\alpha_{g_{i}} x\right)=\bigcup_{i \in I} \bigcup_{h \in H} \mathcal{P}\left(\alpha_{h} \alpha_{g_{i}} x\right)=\mathcal{P}\left(\bigcup_{g \in G} \alpha_{g} x\right)=\mathcal{R}(x) \quad \text { a.e. } x
$$

By $\bar{\sigma}$, we denote the index cocycle corresponding to these choice functions. We will show that if $i, j, i^{\prime}, j^{\prime} \in J$ and $\left[g_{j} g_{i}^{-1}\right]=\left[g_{j^{\prime}} g_{i^{\prime}}^{-1}\right]$, then

$$
\begin{align*}
\bar{\sigma}\left(\alpha_{k g_{i}} x, \alpha_{l g_{j}} x\right) & =\bar{\sigma}\left(\alpha_{k^{\prime} g_{i^{\prime}}} x, \alpha_{l^{\prime} g_{j^{\prime}}} x\right)  \tag{2.1}\\
& =\text { a constant } \quad \text { a.e. } x, \text { and } k, l, k^{\prime}, l^{\prime} \in K
\end{align*}
$$

Let $x, x^{\prime} \in X, k, l, k^{\prime}, l^{\prime} \in K, m \in I$, and let

$$
\begin{aligned}
g_{n} & =\bar{\sigma}\left(\alpha_{k g_{i}} x, \alpha_{l g_{j}} x\right)\left(g_{m}\right) \\
g_{n^{\prime}} & =\bar{\sigma}\left(\alpha_{k^{\prime} g_{i^{\prime}}} x^{\prime}, \alpha_{l^{\prime} g_{j^{\prime}}} x^{\prime}\right)\left(g_{m}\right) .
\end{aligned}
$$

This means $\left(\alpha_{g_{m} l g_{j}} x, \alpha_{g_{n} k g_{i}} x\right) \in \mathcal{S}$ and hence $\left[g_{m} l g_{j}\right]_{H}=\left[g_{n} k g_{i}\right]_{H}$. On the other hand, $\left[g_{m} l g_{j}\right]=\left[g_{m} g_{j}\right]$ and $\left[g_{n} k g_{i}\right]=\left[g_{n} g_{i}\right]$. Therefore, $\left[g_{m} g_{j}\right]_{H}=\left[g_{n} g_{i}\right]_{H}$ and $\left[g_{m^{\prime}} g_{j^{\prime}}\right]_{H}=\left[g_{n^{\prime}} g_{i^{\prime}}\right]_{H}$. By the assumption that $\left[g_{j} g_{i}^{-1}\right]=\left[g_{j^{\prime}} g_{i^{\prime}}^{-1}\right]$, there is an element $q$ in $K$ such that

$$
g_{m}^{-1} H g_{n} \cap g_{m}^{-1} H g_{n^{\prime}} k \neq \emptyset
$$

Choose elements $h$ and $h^{\prime} \in H$ so that $g_{m}^{-1} h g_{n}=g_{m}^{-1} h^{\prime} g_{n^{\prime}} k$, then $h g_{n}=h^{\prime} g_{n^{\prime}} k=$ $h^{\prime} k^{\prime} g_{n^{\prime}}$ for some $k^{\prime} \in K$. Thus, $g_{n}=g_{n^{\prime}}$. Hence we may write

$$
\bar{\sigma}\left(\alpha_{k g_{i}} x, \alpha_{l g_{j}} x\right)=\text { a constant }=\theta\left(\left[g_{j} g_{i}^{-1}\right]\right) \quad \text { a.e. } x, k, l \in K
$$

We will show that for each $\lambda$ in $\Lambda$

$$
\begin{equation*}
\bar{\sigma}(y, x)=e \quad \text { if }(y, x) \in \operatorname{Ker}(\sigma) \quad \text { with } y, x \in A_{\lambda} \tag{2.2}
\end{equation*}
$$

Let $(y, x) \in \operatorname{Ker}(\sigma)$ and $y, x \in A_{\lambda}$, and let $g_{n}=\bar{\sigma}(y, x)\left(g_{m}\right)$, where $n$ and $m \in I$. This means $\left(\alpha_{g_{m}} x, \alpha_{g_{n}} y\right) \in \mathcal{S}$. Using $\left.\mathcal{S}\right|_{A_{\lambda}}=\left.\operatorname{Ker}(\sigma)\right|_{A_{\lambda}} \rtimes_{\alpha} H$, we have $\alpha_{g_{n}} y \in$ $\operatorname{Ker}(\sigma)\left(\alpha_{h}\left(\alpha_{g_{m}} x\right)\right)$ for some $h \in H$. Since $\alpha_{g_{m}} \in N[\operatorname{Ker}(\sigma)],\left(\alpha_{g_{m}} x, \alpha_{g_{m}} y\right) \in$ $\operatorname{Ker}(\sigma)$. Hence, $\left(\alpha g_{n} y, \alpha_{h} \alpha_{g_{m}} y\right) \in \operatorname{Ker}(\sigma)$. Since the action $\alpha_{G}$ is outer, $g_{n}=h g_{m}$, and hence $g_{n}=g_{m}$.

Finally, by (i) and (ii), we see that

$$
\left\{\bar{\sigma}(y, x) \mid(y, x) \in \mathcal{R} \text { and } y, x \in A_{\lambda}\right\} \subset \theta(G / K)
$$

By Lemma 2.2, the set in the left hand side is $\mathbf{r}(\mathcal{R})=G$. Obviously, $\#(\theta(G / K)) \leqslant$ \# $(G / K)$. Thus,

$$
\#(G) \leqslant \#(G / K)
$$

This implies $K=\{e\}$.
Remark 2.12. The collection $\left\{\mathcal{P}, H \subset G, \alpha_{G}\right\}$ satisfying the conditions (ii) and (iii) was obtained by C. Sutherland ([11]). It will be made clear in the next section that the condition (i) in this theorem is a key for proving the uniqueness of $\left\{\mathcal{P}, H \subset G, \alpha_{G}\right\}$.

## 3. THE CONJUGACY CLASS OF $H \subset G$

Throughout this section, we let $\mathcal{R}$ and $\mathcal{S} \subset \mathcal{R}$ be an ergodic measured discrete equivalence relation and an ergodic subrelation admitting an ergodic subrelation $\mathcal{P} \subset \mathcal{S}$ together with a finite group $G$ and a subgroup $H \subset G$ and an action $g \in G \mapsto \alpha_{g} \in N[\mathcal{P}]$ satisfying the following conditions:
(i) $H$ does not contain any normal subgroup $\neq\{e\}$ of $G$;
(ii) $\alpha_{G}$ is outer;
(iii) $\mathcal{R}=\mathcal{P} \rtimes_{\alpha} G$, and $\mathcal{S}=\mathcal{P} \rtimes_{\alpha} H$.

In the previous section we showed that every ergodic measured discrete equivalence relation and an ergodic subrelation with finite index admits the system $\left\{\mathcal{P}, H \subset G, \alpha_{G}\right\}$ satisfying the above conditions (i)-(iii). In this section we will show that the conjugacy class of the pair of the group $G$ and the subgroup $H$ is uniquely determined by the inclusion data $\mathcal{S} \subset \mathcal{R}$.

Thoerem 3.1. The conjugacy class of the pair of the finite group $G$ and the subgroup $H$ depends only on the orbit equivalence class of the pair of $\mathcal{R}$ and $\mathcal{S}$.

In fact, we will prove that the pair $H$ and $G$ is conjugate with the pair of $\mathbf{r}(\mathcal{S})$ and $\mathbf{r}(\mathcal{R})$. Then in view of Lemma 2.5, the latter pair depends only on the orbit equivalence class of the pair of $\mathcal{R}$ and $\mathcal{S}$. After preparing several lemmas and a proposition, we will prove this.

Throughout this section, we choose and fix a Rohlin set $F$ for the free action $\alpha_{G}$, that is,

$$
\bigcup_{g \in G} \alpha_{g} F=X \quad \text { (disjoint union). }
$$

We let $G / H$ be the coset space of the group $G$ by the subgroup $H$, and choose and fix representatives $g_{i} \in G, i \in I$, so that $G=\left\{\left[g_{i}\right]_{H} \mid i \in I\right\}$, where $g_{0}=e$ and $[g]_{H}=H g$ for $g \in G$. We define the transformations $\varphi_{i} \in[\mathcal{R}], i \in I$ by

$$
\varphi_{i} x=\alpha_{h g_{i} h^{-1}} x, \quad \text { for } x \in \bigcup_{j \in I} \alpha_{h g_{j}}(F), \quad h \in H
$$

We set for each $h \in H$,

$$
F_{h}=\bigcup_{i \in I} \alpha_{h g_{i}}(F)
$$

We note that $\varphi_{i}\left(\alpha_{h g_{j}}(F)\right)=\alpha_{h g_{i} g_{j}}(F)$.
Lemma 3.2. $\left\{\varphi_{i} \mid i \in I\right\}$ is the set of choice functions of $\mathcal{S} \subset \mathcal{R}$.
Proof. We will show that if $\left(\varphi_{i} x, \varphi_{k} x\right) \in \mathcal{S}$, then $i=k$ for a.e. $x$. Let $u \in F, j \in I$ and let $h \in H$ be such that $x=\alpha_{h g_{j}} u$. Then $\left(\varphi_{i} x, \varphi_{k} x\right)=$ $\left(\alpha_{h g_{i} g_{j}} u, \alpha_{h g_{k} g_{j}} u\right) \in \mathcal{S}$. So, by (iii) there is an element $h^{\prime}$ in $H$ such that $\left(\alpha_{h^{\prime}} \alpha_{h g_{i} g_{j}} u, \alpha_{h g_{k} g_{j}} u\right) \in \mathcal{P}$. By (ii), $h^{\prime} h g_{i} g_{j}=h g_{k} g_{j}$. Hence $g_{i}=g_{k}$.

Next, let $g \in G$ and $x=\alpha_{h g_{j}} u$, where $u \in F, h \in H$. Then, $\alpha_{g} x=\alpha_{g h g_{j}} u=$ $\alpha_{h^{\prime} g_{l} g_{j}} u$, where $l \in I, h^{\prime} \in H$ with $g h=h^{\prime} g_{l}$. Hence,

$$
\alpha_{g} x=\alpha_{h^{\prime} h^{-1}} \cdot \alpha_{h g_{l} g_{j}} u=\alpha_{h^{\prime} h^{-1}} \varphi_{l}(x) \in \mathcal{S}\left(\varphi_{l}(x)\right)
$$

By the condition (iii), $\mathcal{R}(x)=\bigcup_{l \in I} \mathcal{S}\left(\varphi_{l} x\right)$ a.e. $x$.
By $\sigma$, we denote the index cocycle corresponding to the choice functions $\varphi_{i}$, $i \in I$.

Lemma 3.3. $\sigma\left(\alpha_{h^{\prime}} y, \alpha_{h} x\right)=\sigma(y, x) \quad$ a.e. $(x, y) \in \mathcal{R}, h, h^{\prime} \in H$.
Proof. Let $(y, x) \in \mathcal{R}, k \in I$ and $h$ and $h^{\prime} \in H$. Set $l=\sigma(y, x)(k)$. It is easy to see

$$
\varphi_{l} \alpha_{g}=\alpha_{g} \varphi_{l} \quad \forall g \in H \text { and } \forall l \in I
$$

Therefore by the condition (iii), $\left(\varphi_{k}\left(\alpha_{h} x\right), \varphi_{k}(x)\right)=\left(\alpha_{h} \varphi_{k}(x), \varphi_{k} x\right) \in \mathcal{S}$ and $\left(\varphi_{l}\left(\alpha_{h^{\prime}} x\right), \varphi_{l}(x)\right)=\left(\alpha_{h^{\prime}} \varphi_{l}(x), \varphi_{l} x\right) \in \mathcal{S}$. Hence

$$
\left(\varphi_{k} x, \varphi_{l} y\right) \in \mathcal{S} \quad \text { if and only if } \quad\left(\varphi_{k} \alpha_{h} x, \varphi_{l} \alpha_{h^{\prime}} y\right) \in \mathcal{S}
$$

Thus, $\left.l=\sigma\left(\alpha_{h^{\prime}} y, \alpha_{h} x\right)\right)(k)$.
Lemma 3.4. For each $h \in H$,

$$
\left.\mathcal{P}\right|_{F(h)}=\left.\operatorname{Ker}(\sigma)\right|_{F(h)} .
$$

Proof. To see the inclusion $\left.\left.\mathcal{P}\right|_{F(h)} \subset \operatorname{Ker}(\sigma)\right|_{F(h)}$, we let $x=\alpha_{h g_{i}} u$ and $y=\alpha_{h g_{j}} v$, where $h \in H, u, v \in F$, and suppose $(x, y) \in \mathcal{P}$. Since $\alpha_{h g_{l} h^{-1}} \in N[\mathcal{P}]$, we have $\left(\varphi_{l} x, \varphi_{l} y\right)=\left(\alpha_{h g_{l} g_{i}} u, \alpha_{h g_{l} g_{j}} v\right) \in \mathcal{P}, \forall l \in I$. Thus, $l=\sigma(y, x)(l), \forall l \in I$. We will show the converse inclusion. We let $h \in H, u \in F$, set $x=\alpha_{h g_{i}} u$, $y=\alpha_{h g_{j}} v$ and suppose $\sigma(x, y)=e$. By Lemma 3.3,

$$
e=\sigma(x, y)=\sigma\left(\alpha_{h g_{i}} u, \alpha_{h g_{j}} v\right)=\sigma\left(\alpha_{g_{i}} u, \alpha_{g_{j}} v\right) .
$$

This implies $\left(\varphi_{l}\left(\alpha_{g_{i}} u\right), \varphi_{l}\left(\alpha_{g_{j}} v\right)\right) \in \mathcal{S}, \forall l \in I$ and hence, $\left(\alpha_{g_{l} g_{i}} u, \alpha_{g_{l} g_{j}} v\right) \in \mathcal{S}$, $\forall l \in I$. So, there exist elements $h_{l}$ in $H, l \in I$ such that $\left(\alpha_{g_{l} g_{i}} u, \alpha_{h_{l}} \alpha_{g_{l} g_{j}} v\right) \in \mathcal{P}$. In particular, $\left(\alpha_{g_{i}} u, \alpha_{g_{j}} v\right) \in \mathcal{S}$, so we have an element $\bar{h}$ in $H$ such that

$$
\left(\alpha_{g_{i}} u, \alpha_{\bar{h} g_{i}} u\right) \in \mathcal{S} \quad \text { and } \quad\left(\alpha_{\overline{h g_{i}}} u, \alpha_{g_{j}} v\right) \in \mathcal{P} .
$$

Therefore, $\alpha_{g_{l} \bar{h}^{-1}}$ and $\alpha_{h_{l} g_{l}}$ map the $\mathcal{P}$-orbit $\mathcal{P}\left(\alpha_{\bar{h} g_{i}} u\right)=\mathcal{P}\left(\alpha_{g_{j}} v\right)$ onto the $\mathcal{P}$-orbit $\mathcal{P}\left(\alpha_{g_{l} g_{i}} u\right)=\mathcal{P}\left(\alpha_{h_{l} g_{l} g_{j}} v\right)$. By the condition (ii), we see $h_{l} g_{l}=g_{l} \bar{h}^{-1} \in H, \forall l \in I$. Namely, $g_{l} \bar{h}^{-1} g_{l}^{-1}, \forall l \in I$. Then, by the condition (i), we see $\bar{h}=e$. Thus, $\left(\alpha_{g_{i}} u, \alpha_{h g_{j}} v\right) \in \mathcal{P}$. Hence, $(x, y)=\left(\alpha_{h g_{i}} u, \alpha_{h g_{j}} v\right) \in \mathcal{P}$.

Lemma 3.5. $\operatorname{Ker}(\sigma)$ is ergodic.
Proof.

$$
\begin{array}{ll}
\left.\operatorname{Ker}(\sigma)\right|_{F(h)}=\left.\mathcal{P}\right|_{F(h)}, & \forall h \in H \text { (use Lemma 3.4), } \\
\sigma\left(\alpha_{h} x, x\right)=e, & \text { a.e. } x, \forall h \in H \text { (use Lemma 3.3) }
\end{array}
$$

Hence, $\operatorname{Ker}(\sigma)$ is ergodic.

Lemma 3.6. The measurable function $u \in F \mapsto \sigma\left(\alpha_{g_{j}} u, u\right) \in \Sigma \#(I)$ is constant a.e., $\forall j \in I$.

Proof. Let $u, v \in F$ and suppose $(u, v) \in \mathcal{P}$. Then, since $\alpha_{g_{j}} \in N[\mathcal{P}]$, $\left(\alpha_{g_{j}} u, \alpha_{g_{j}} v\right) \in \mathcal{P}$. Applying Lemma 3.4, $\sigma(u, v)=\sigma\left(\alpha_{g_{j}} v, \alpha_{g_{j}} u\right)=e$. On the other hand, $\sigma\left(\alpha_{g_{j}} v, v\right)=\sigma\left(\alpha_{g_{j}} v, \alpha_{g_{j}} u\right) \sigma\left(\alpha_{g_{j}} u, u\right) \sigma(u, v)$. So, $\sigma\left(\alpha_{g_{j}} v, v\right)=\sigma\left(\alpha_{g_{j}} u, u\right)$. In other words, the function $u \in F \mapsto \sigma\left(\alpha_{g_{j}} u, u\right)$ is $\left.\mathcal{P}\right|_{F}$-invariant. The ergodicity of $\left.\mathcal{P}\right|_{F}$ implies that

$$
\sigma\left(\alpha_{g_{j}} u, u\right)=\text { constant } \quad \text { a.e. } u \in F .
$$

By $\theta_{g_{j}}$, we denote the constant $\sigma\left(\alpha_{g_{j}} u, u\right), u \in F$.
Proposition 3.7. Let $h$ and $h^{\prime} \in H$. Then, $\sigma(u, v)=$ a constant a.e. $(u, v) \in \mathcal{P}$ with $u \in F(h)$ and $v \in F\left(h^{\prime}\right)$. Moreover, this constant depends only on $h^{-1} h^{\prime}$. Denoting this constant by $\theta_{h^{-1} h^{\prime}}$, then the map $h \in H \mapsto \theta_{h} \in \Sigma_{\sharp(I)}$ gives a group into isomorphism.

Proof. Let $h, h^{\prime} \in H, u, u_{1} \in F(h)$ and $v, v_{1} \in F\left(h^{\prime}\right)$ and suppose that $(u, v),\left(v, v_{1}\right)$ and $\left(v_{1}, u_{1}\right) \in \mathcal{P}$. Then, by lemma 3.5, we see $\sigma\left(v_{1}, v\right)=e$ and $\sigma\left(u, u_{1}\right)=e$. So, $\sigma(u, v)=\sigma\left(u, u_{1}\right) \sigma\left(u_{1}, v_{1}\right) \sigma\left(v_{1}, v\right)=\sigma\left(u_{1}, v_{1}\right)$. Since both of $\left.\mathcal{P}\right|_{F(h)}$ and $\left.\mathcal{P}\right|_{F\left(h^{\prime}\right)}$ are ergodic, $\sigma(u, v)=$ constant a.e. $(u, v) \in \mathcal{P}$ with $u \in F(h)$ and $v \in F\left(h^{\prime}\right)$. By $\theta_{h, h^{\prime}}$, we denote this constant $\sigma(u, v)$, where $u \in F(h), v \in$ $F\left(h^{\prime}\right)$. Since $\sigma$ is a cocycle, $\theta$ satisfies the cocycle property

$$
\begin{equation*}
\theta_{h, h^{\prime}} \cdot \theta_{h^{\prime}, h^{\prime \prime}}=\theta_{h, h^{\prime \prime}}, \quad h, h^{\prime} \in H \tag{3.1}
\end{equation*}
$$

Let us choose $u, z \in F(e), v \in F\left(h^{\prime}\right)$ and $w \in F(h)$ so that $(u, v),(v, w)$ and $(w, z) \in \mathcal{P}$. Then,

$$
e=\sigma(z, u)=\sigma(z, w) \sigma(w, v) \sigma(v, u)=\theta_{e, h} \theta_{h, h^{\prime}} \theta_{h^{\prime}, e}
$$

Therefore, $\theta_{h, h^{\prime}}=\theta_{h, e} \theta_{e, h^{\prime}}$. Here, set $\theta_{h^{-1}}=\theta_{h, e}$, then, $\theta_{e, h}=\theta_{h}$, and hence $\theta_{h}^{-1}=\theta_{h^{-1}}$ and $\theta_{h, h^{\prime}}=\theta_{h}^{-1} \theta_{h^{\prime}}$.

We will show the left invariance of $\theta_{h, h^{\prime \prime}}$ in the sense that

$$
\begin{equation*}
\theta_{h, e}=\theta_{\bar{h} h, \bar{h}}, \quad h, \bar{h} \in H \tag{3.2}
\end{equation*}
$$

Choose $(u, v) \in \mathcal{P}$ with $u \in F(e)$ and $v \in F(h)$. Then, $\left(\alpha_{\bar{h}} u, \alpha_{\bar{h}} v\right) \in \mathcal{P}$ and hence,

$$
\theta_{\bar{h} h, \bar{h}}=\sigma\left(\alpha_{\bar{h}} v, \alpha_{\bar{h}} u\right)=\sigma\left(\alpha_{\bar{h}} v, v\right) \sigma(v, u) \sigma(u, \bar{h} u)^{(\text {Lemma 3.3) }} \theta_{h, e}
$$

This makes $\theta$ an homomorphism. In fact, if $h, \bar{h} \in H$, then

$$
\theta_{h} \cdot \theta_{\bar{h}}=\theta_{h^{-1}, e} \cdot \theta_{\bar{h}^{-1}, e} \stackrel{(3.2)}{=} \theta_{\bar{h}^{-1} h^{-1}, \bar{h}^{-1}} \cdot \theta_{\bar{h}^{-1}, e} \stackrel{\text { cocycle property }}{=}(\mathrm{iii}) \theta_{\bar{h}^{-1} h^{-1}, e}=\theta_{h \bar{h}} .
$$

Finally, we will show that the map $h \in H \mapsto \theta_{h} \in \mathcal{S}_{\sharp(I)}$ is injective. Let $h \in H$ and suupose $\theta_{h}=e$. Choose a point $(u, v) \in \mathcal{P}$ such that $u \in F(e)$ and $v \in \mathcal{P}(h)$. Then,

$$
\sigma\left(\alpha_{h}^{-1} v, u\right)=\sigma\left(\alpha_{h}^{-1} v, v\right) \sigma(v, u)=e \cdot \theta_{h}^{-1}=e
$$

Since $u$ and $\alpha_{h}^{-1} v \in F(e)$, it follows from Lemma 3.4 that $\left(u, \alpha_{h}^{-1} v\right) \in \mathcal{P}$. Hence, $\left(\alpha_{h}^{-1} v, v\right) \in \mathcal{P}$. Since the action $\alpha_{G}$ is outer over $\mathcal{P}$, we see $h=e$.

By $\theta_{h}$, we denote the constant $\sigma(u, v), u \in F(e), v \in F(h), h \in H$.
Lemma 3.8. $\theta_{g_{j}} \neq e$ if $g_{j} \neq e$.
Proof. Let $j \in I$ be such that $\theta_{g_{j}}=e$. If $u \in F$ then since $\alpha_{g_{j}} u \in F(e)$, it follows from Lemma 3.4 that $\left(u, \alpha_{g_{j}} u\right) \in \mathcal{P}$. Hence, $g_{j}=e$, because $\alpha_{G}$ is outer.

Lemma 3.9. Let $h, \bar{h} \in H$ and let $i, k \in I$. If $g_{i} h=\bar{h} g_{k}$ then $\theta_{g_{i}} \theta_{h}=\theta_{\bar{h}} \theta_{g_{k}}$.
Proof. Let $h, \bar{h} \in H$ and let $i, k \in I$. Suppose $g_{i} h=\bar{h} g_{k}$. Using the ergodicity of $\mathcal{P}$, we have for a.e. $\omega \in F(h)$, a point $u \in F$ such that $(u, \omega) \in \mathcal{P}$. Then, $\left(\alpha_{g_{i}} u, \alpha_{\overline{h_{g} h^{-1}}} \omega\right) \in \mathcal{P}$. Hence,

$$
\begin{aligned}
\sigma\left(\alpha_{g_{i}} u, \alpha_{h}^{-1} \omega\right) & =\sigma\left(\alpha_{g_{i}} u, \alpha_{\bar{h} g_{k} h^{-1}} \omega\right) \sigma\left(\alpha_{\bar{h} g_{k} h^{-1}} \omega, \alpha_{g_{k} h^{-1}} \omega\right) \sigma\left(\alpha_{g_{k} h^{-1}} \omega, \alpha_{h^{-1}} \omega\right) \\
& =\theta_{e, \bar{h}} \cdot e \cdot \theta_{g_{k}}=\theta_{\bar{h}} \cdot \theta_{g_{k}} .
\end{aligned}
$$

On the other hand,

$$
\sigma\left(\alpha_{g_{i}} u, \alpha_{h}^{-1} \omega\right)=\sigma\left(\alpha_{g_{i}} u, u\right) \sigma(u, \omega) \sigma\left(\omega, \alpha_{h}^{-1} \omega\right)=\theta_{g_{i}} \cdot \theta_{e, h} \cdot e=\theta_{g_{i}} \theta_{h}
$$

Lemma 3.10. Let $i, j, k \in I$ and $h \in H$. If $g_{i} g_{j}=h g_{k}$ then $\theta_{g_{i}} \theta_{g_{j}}=\theta_{h} \theta_{g_{k}}$.
Proof. Suppose $g_{i} g_{j}=h g_{k}$. Using the ergodicity of $\mathcal{P}$, we have for a.e. $u \in F$ a point $\omega \in F$ such that $\left(\alpha_{g_{j}} u, \omega\right) \in \mathcal{P}$. Then, since $\alpha_{g_{i}} \in N[\mathcal{P}]$, we see $\left(\alpha_{h g_{k}} u, \alpha_{g_{i}} \omega\right)=\left(\alpha_{g_{i}} \alpha_{g_{j}} u, \alpha_{g_{i}} \omega\right) \in \mathcal{P}$. Since $\alpha_{h g_{k}} u=\alpha_{g_{i}}\left(\alpha_{g_{j}} u\right) \in F(h)$ and $\alpha_{g_{i}} \omega \in F(e)$,

$$
\sigma\left(\alpha_{h g_{k}} u, \alpha_{g_{i}} \omega\right)=\theta_{h, e}=\theta_{h^{-1}}
$$

The cocycle equation of $\sigma$ implies

$$
\begin{aligned}
\theta_{h} \cdot \theta_{g_{k}} & =\sigma\left(\alpha_{g_{i}} \omega, \alpha_{h g_{k}} u\right) \sigma\left(\alpha_{h g_{k}} u, \alpha_{g_{k}} u\right) \sigma\left(\alpha_{g_{k}} u, u\right)=\sigma\left(\alpha_{g_{i}} \omega, u\right) \\
& =\sigma\left(\alpha_{g_{i}} \omega, \omega\right) \sigma\left(\omega, \alpha_{g_{j}} u\right) \sigma\left(\alpha_{g_{j}} u, u\right)=\theta_{g_{i}} \theta_{g_{j}} .
\end{aligned}
$$

This lemma allows us to define the map $g \in G \mapsto \theta_{g} \in \Sigma_{\#(I)}$ as follows.

Definition 3.11. For $h, \bar{h} \in H$ and $i, j \in I$, we define

$$
\theta_{h g_{j}}=\theta_{h} \theta_{g_{j}} \quad \text { and } \quad \theta_{g_{i} \bar{h}}=\theta_{g_{i}} \theta_{\bar{h}} .
$$

We note that $\theta_{g_{i}^{-1}}=\theta_{g_{i}}^{-1}$. Because, $g_{i}^{-1}$ is of the form $h g_{k}$ for some $h \in H$ and $k \in I . g_{k} g_{i}=h^{-1}$ implies $\theta_{g_{k}} \theta_{g_{i}}=\theta_{h}^{-1}=\theta_{h}^{-1}$, and hence $\theta_{g_{i}}^{-1}=\theta_{h} \theta_{g_{k}}=$ $\theta_{h g_{k}}=\theta_{g_{i}^{-1}}$.

Lemma 3.12. (i) $\sigma(u, v) \in \theta_{G}$ a.e. $(u, v) \in \mathcal{R}$;
(ii) $\sigma(u, v) \in \theta_{H}$ a.e. $(u, v) \in \mathcal{S}$.

Proof. (i) Since $\mathcal{R}=\mathcal{P} \rtimes_{\alpha} G$, it is enough to see that if $h, \bar{h} \in H$ and $i, j \in I$ and if $u \in F$ and $\left(v, \alpha_{\bar{h} g_{i} h g_{j}} u\right) \in \mathcal{P}$ then $\sigma\left(v, \alpha_{g_{j}} u\right) \in \theta_{G}$. In fact,

$$
\begin{array}{r}
\sigma\left(v, \alpha_{g_{j}} u\right)=\sigma\left(v, \alpha_{\bar{h} g_{i}}\left(\alpha_{g_{j}} u\right)\right) \sigma\left(\alpha_{\bar{h}}\left(\alpha_{g_{i} g_{j}} u\right), \alpha_{g_{i} g_{j}} u\right) \sigma\left(\alpha_{g_{i} g_{j}} u, \alpha_{g_{j}} u\right) \\
\in \theta_{H} \cdot \sigma\left(\alpha_{g_{i} g_{j}} u, \alpha_{g_{j}} u\right)
\end{array}
$$

and, since $g_{i} g_{j}=h g_{k}$ for some $h \in H$,

$$
\sigma\left(\alpha_{g_{i} g_{j}} u, \alpha_{g_{j}} u\right)=\sigma\left(\alpha_{h}\left(\alpha_{g_{k}} u\right), \alpha_{g_{j}} u\right)=\sigma\left(\alpha_{g_{k}} u, \alpha_{g_{j}} u\right)=\sigma\left(\alpha_{g_{k}} u, u\right) \sigma\left(u, \alpha_{g_{j}} u\right) \in \theta_{G} .
$$

(ii) In the proof of (i), consider the case where $i=0$, that is $g_{i}=e$. Then $g_{k}=g_{j}$ and $\sigma\left(v, \alpha_{h g_{j}} u\right)=\theta_{h^{\prime-1} \bar{h}} \in \theta_{H}$.

Lemma 3.13. The map $\theta: g \mapsto \theta_{g} \in \Sigma_{\#(I)}$ is an into group isomorphism.
Proof. Let $h, h^{\prime} \in H$ and $i, i^{\prime} \in I$, and set $g=h g_{j}, g^{\prime}=h^{\prime} g_{i}$. By the definition of $\theta_{G}$,

$$
\begin{aligned}
\theta_{g^{\prime} g} & =\theta_{h^{\prime}} \bar{h} \theta_{g_{k} g_{j}} \quad\left(\text { where } g_{i} h=\bar{h} g_{k}, \bar{h} \in H\right) \\
& =\theta_{h^{\prime}} \theta_{\bar{h}} \theta_{g_{k}} \theta_{g_{j}} \quad \text { (use Proposition 3.7 and Lemma 3.10) } \\
& =\theta_{h^{\prime}} \theta_{g_{i}} \theta_{h} \theta_{g_{j}} \quad \text { (use Lemma 3.9) } \\
& =\theta_{g^{\prime}} \theta_{g} .
\end{aligned}
$$

In order to see that the map $\theta$ is injective, let $h \in H$ and $j \in I$ and suppose $\theta_{h g_{j}}=e$. Since $\mathcal{P}$ is ergodic, we obtain for a.e. $u \in F$ a point $v \in \alpha_{h}(F)$ with $(u, v) \in \mathcal{P}$. Then,

$$
\sigma\left(\alpha_{h}^{-1} v, \alpha_{g_{j}} u\right)=\sigma\left(\alpha_{h}^{-1} v, v\right) \sigma(v, u) \sigma\left(u, \alpha_{g_{j}} u\right)=\theta_{h}^{-1} \theta_{g_{j}}^{-1}
$$

Since $\alpha_{h}^{-1} v$ and $\alpha_{g_{j}} u \in F(e)$, it follows from Lemma 3.4 that $\left(\alpha_{h}^{-1} v, \alpha_{g_{j}} u\right) \in$ $\mathcal{P}$. Hence $\left(\alpha_{g_{j}}^{-1} \alpha_{h}^{-1} v, u\right) \in \mathcal{P}$. On the other hand, since $(u, v) \in \mathcal{P}$, we have $\left(\alpha_{g_{j}}^{-1} \alpha_{h}^{-1} v, v\right) \in \mathcal{P}$. Since $\alpha_{G}$ is outer, $g_{j}^{-1} h^{-1}=e$. Therefore, $g_{j}=e$ and $h=e$. Thus $h g_{j}=e$.

Proof of Theorem 3.1. In fact, by Lemma 3.11 and Lemma 3.12 we see that $\theta(G)=\mathbf{r}(\mathcal{R})$ and $\theta(H)=\mathbf{r}(\mathcal{S})$.
4. CANONICAL SYSTEM $\left\{\mathcal{P}, H \subset G, \alpha_{G}\right\}$

Continued to the previous section, we are going to show that the subrelation $\mathcal{P}$ and the action $\alpha_{G}$ depend only on the orbit equivalence class of the pair of $\mathcal{R}$ and $\mathcal{S}$.

Theorem 4.1. Suppose ergodic measured discrete equivalence relations $\mathcal{R}$ and $\mathcal{R}^{\prime}$ and ergodic subrelations $\mathcal{S} \subset \mathcal{R}$ and $\mathcal{S}^{\prime} \subset \mathcal{R}^{\prime}$ admit the collection $\left\{\mathcal{P}, \alpha_{G}\right.$, $H \subset G\}$ and $\left\{\mathcal{P}^{\prime}, \alpha_{G^{\prime}}^{\prime}, H^{\prime} \subset G^{\prime}\right\}$ respectively satisfying the conditions (i), (ii) and (iii) in Section 3. If the pairs $\{\mathcal{R}, \mathcal{S}\}$ and $\left\{\mathcal{R}^{\prime}, \mathcal{S}^{\prime}\right\}$ are orbit equivalence then there exists a measure isomorphism $\varphi: X \mapsto X^{\prime}$ and a group isomoprphism $\gamma: G \mapsto G^{\prime}$ such that:
(i) $\gamma(H)=H^{\prime}$;
(ii) $\varphi[\mathcal{P}] \varphi^{-1}=\left[\mathcal{P}^{\prime}\right]$;
(iii) $\varphi \alpha_{g} \varphi^{-1}=\alpha_{\gamma(g)}^{\prime}, \forall g \in G$.

After preparing the Propositions 4.2 and 4.3 , we will prove this theorem.
Throughout this section we assume that $\mathcal{R}$ and $\mathcal{S}$ (respectively $\mathcal{R}^{\prime}$ and $\mathcal{S}^{\prime}$ ) satisfy the conditions in Theorem 4.1.

Proposition 4.2. Let $\left\{\mathcal{P}, H \subset G, \alpha_{G}\right\}$ satisfy the conditions (i), (ii) and (iii) for the pair $\{\mathcal{R}, \mathcal{S}\}$. Then there exists an index cocycle $\sigma$ of $\mathcal{S} \subset \mathcal{R}$, an action $g \in \mapsto \beta_{g} \in N[\operatorname{Ker}(\sigma)]$ and $a \varphi \in[\mathcal{S}]$ satisfying the following conditions:
(i) $\operatorname{Ker}(\sigma)$ is ergodic;
(ii) $\beta_{G}$ is outer;
(iii) $\sigma\left(\beta_{g} x, x\right)=g, \forall g \in G$, a.e. $x$;
(iv) $\varphi[\mathcal{P}] \varphi^{-1}=[\operatorname{Ker}(\sigma)]$;
(v) $\varphi \alpha_{g} \varphi^{-1}=\beta_{g}, g \in G$.

Proof. We choose and fix representatives $g_{j}, j \in I$, from the coset space $G / H$, where $g_{0}=e$ and let $\sigma$ be the index cocycle of $\mathcal{S} \subset \mathcal{R}$ constructed in the proof of Theorem 3.1. We choose and fix a Rohlin set $F$ for the free action $\alpha_{G}$ and define the sets $F(h), h \in H$, as in the proof of Theorem 3.1. By Lemma 3.3 and Lemma 3.4,

$$
\left.\mathcal{P}\right|_{F(e)}=\left.\operatorname{Ker}(\sigma)\right|_{F(e)}
$$

and

$$
\left(\alpha_{h} x, x\right) \in \operatorname{Ker}(\sigma), \quad \text { a.e. } x, h \in H
$$

Since $\alpha_{h}(F(e))=F(h)$ and $X=\bigcup_{h \in H} F(h)$, and since $\left.\mathcal{P}\right|_{F(e)}$ is ergodic, we see that $\operatorname{Ker}(\sigma)$ is ergodic.

What we are going to do is to define the action $\beta_{G}$ in the theorem. For this, set

$$
\beta_{g_{j}} x=\alpha_{g_{j}} x, \quad x \in F, j \in J
$$

then $\sigma\left(\beta_{g_{j}} x, x\right)=\theta_{g_{j}}, x \in F$. Using the ergodicity of $\mathcal{P}$, we get for each $h \in H$ a $\beta_{h} \in[\mathcal{P}]_{*}$ such that $\beta_{h}\left(\alpha_{g_{j}} F\right)=\alpha_{h g_{j}}(F), \forall j \in I$. We set for $h \in H$, and $j \in I$,

$$
\beta_{h g_{j}} u=\beta_{h} \beta_{g_{j}} u, \quad u \in F
$$

then

$$
\sigma\left(\beta_{h g_{j}} u, u\right)=\sigma\left(\beta_{h g_{j}} u, \beta_{g_{j}} u\right) \sigma\left(\beta_{g_{j}} u, u\right)=\theta_{h} \theta_{g_{j}}=\theta_{h g_{j}}
$$

We define the transformations $\beta_{g} \in[\mathcal{S}], g \in G$, by

$$
\beta_{g} x=\beta_{g \bar{g}} \beta_{\bar{g}}^{-1} x, \quad x \in \alpha_{\bar{g}}(F), \forall g \in G
$$

It is easy to see that $\beta_{G}$ is an action (i.e. $\beta_{g g^{\prime}}=\beta_{g} \beta_{g^{\prime}}$ ). If $x \in \alpha_{\bar{g}}(F)$ then

$$
\begin{array}{rlr}
\sigma\left(\beta_{g} x, x\right) & =\sigma\left(\beta_{g \bar{g}}\left(\beta_{\bar{g}}^{-1} x\right), \beta_{\overline{\bar{g}}}^{-1} x\right) \sigma\left(\beta_{\bar{g}}^{-1} x, x\right) \\
& =\theta_{g \bar{g}} \cdot \sigma\left(\beta_{\bar{g}} y, y\right)^{-1}, \quad \text { where } y=\beta_{\bar{g}}^{-1} x \\
& =\theta_{g \bar{g}} \cdot \theta_{\bar{g}}^{-1}=\theta_{g \bar{g} \cdot \bar{g}^{-1}}=\theta_{g} . &
\end{array}
$$

Hence, if $(x, y) \in \operatorname{Ker}(\sigma)$ then $\sigma\left(\beta_{g} x, \beta_{g} y\right)=e, \forall g \in G$, so that $\beta_{G} \subset \operatorname{Ker}(\sigma) \cap[\mathcal{R}]$. Here we note that the subrelation $\operatorname{Ker}(\sigma)$ is characterized as follows. If $h, \bar{h} \in H$ and $(x, y) \in \mathcal{R}$ with $x \in F(h)$ and $y \in F(\bar{h})$ then $(x, y) \in \operatorname{Ker}(\sigma)$ if and only if $\left(\alpha_{\bar{h} h^{-1}} x, y\right) \in \mathcal{P}$. In fact,

$$
\sigma(y, x)=\sigma\left(y, \alpha_{\bar{h} h^{-1}} x\right) \sigma\left(\alpha_{\bar{h} h^{-1}} x, x\right)=\sigma\left(y, \alpha_{\bar{h} h^{-1}} x\right)
$$

(use Lemma 3.3) and hence,

$$
(y, x) \in \operatorname{Ker}(\sigma) \Leftrightarrow\left(y, \alpha_{\bar{h} h^{-1}} x\right) \in \mathcal{P} \quad \text { (use Lemma 3.5). }
$$

Finally, we define the transformation $\varphi \in[\mathcal{S}]$ by

$$
\begin{array}{ll}
\varphi x=x, & x \in F(e) \\
\varphi \alpha_{h} x=\beta_{h} x, & x \in F(e), h \in H
\end{array}
$$

We are going to prove

$$
\begin{align*}
& \varphi \alpha_{g}=\beta_{g} \varphi \quad \forall g \in G,  \tag{4.1}\\
& \varphi[\operatorname{Ker}(\sigma)] \varphi^{-1}=[\mathcal{P}] . \tag{4.2}
\end{align*}
$$

To see (4.1), if $u \in F, h \in H, j \in I$ and $g=\bar{h} g_{i}$, with $i \in I$ and $\bar{h} \in H$, and if $x=\alpha_{h g_{j}} u \in F(h)$ then

$$
\begin{aligned}
\alpha_{g} x & =\alpha_{\bar{h} g_{i} h g_{j}} \\
& =\alpha_{\bar{h} h^{\prime} g_{k} g_{j}} u \quad\left(\text { where } h^{\prime} \in H \text { and } g_{i} h=h^{\prime} g_{k}\right) \\
& =\alpha_{\bar{h} h^{\prime} h^{\prime \prime} g_{l}} u \quad\left(\text { where } h^{\prime \prime} \in H \text { and } g_{k} g_{j}=h^{\prime \prime} g_{l}\right) .
\end{aligned}
$$

Hence

$$
\begin{aligned}
\varphi \alpha_{g} x & =\varphi \alpha_{\bar{h} h^{\prime} h^{\prime \prime} g_{l}} u=\beta_{\bar{h} h^{\prime} h^{\prime \prime}} \alpha_{g_{l}} u=\beta_{\bar{h} h^{\prime} h^{\prime \prime} g_{l}} u \\
& =\beta_{\bar{h} g_{i}} \beta_{h g_{j}} u=\beta_{g} \varphi \alpha_{h g_{j}} u=\beta_{g} \varphi x
\end{aligned}
$$

To see (4.2), if $h, \bar{h} \in H, i, j \in I$ and $u, v \in F$ and if $x=\alpha_{h g_{i}} u, y=\alpha_{\overline{h g_{j}}} v$, then

$$
\begin{aligned}
(x, y) \in \operatorname{Ker}(\sigma) & \Leftrightarrow\left(\alpha_{\bar{h} h^{-1}} x, y\right) \in \mathcal{P} \\
& \Leftrightarrow\left(\alpha_{g_{i}} u, \alpha_{g_{j}} v\right) \in \mathcal{P} \\
& \Leftrightarrow(\varphi x, \varphi y)=\left(\beta_{h} \alpha_{g_{i}} u, \beta_{\bar{h}} \alpha_{g_{j}} v\right) \in \mathcal{P} .
\end{aligned}
$$

Proposition 4.3. Let $\sigma$ and $\sigma^{\prime}$ be index cocycles of $\mathcal{S} \subset \mathcal{R}$ having ergodic kernels $\operatorname{Ker}(\sigma)$ and $\operatorname{Ker}\left(\sigma^{\prime}\right)$ respectively. Assume that the outer actions $g \in G \mapsto$ $\beta_{g} \in N[\operatorname{Ker}(\sigma)]$ and $g \in G \mapsto \beta_{g}^{\prime} \in N[\operatorname{Ker}(\sigma)]$ satisfy the following conditions:
(i) $\mathcal{R}=\operatorname{Ker}(\sigma) \rtimes_{\beta} G, \quad \mathcal{S}=\operatorname{Ker}(\sigma) \rtimes_{\beta} H$, $\mathcal{R}=\operatorname{Ker}\left(\sigma^{\prime}\right) \rtimes_{\beta^{\prime}} G, \quad \mathcal{S}=\operatorname{Ker}\left(\sigma^{\prime}\right) \rtimes_{\beta} H$;
(ii) $\sigma\left(\beta_{g} x, x\right)=a$ constant $=\theta_{g}, \quad \forall g \in G$, a.e. $x$, $\sigma^{\prime}\left(\beta_{g}^{\prime} x, x\right)=a$ constant $=\theta_{g}^{\prime}, \quad \forall g \in G$, a.e. $x$.
Then, there exists an invertible non-singular transformation $\varphi$ and a group automorphism $\gamma$ in $\operatorname{Aut}(G) \cap \operatorname{Aut}(H)$ such that

$$
\begin{aligned}
& \varphi[\operatorname{Ker}(\sigma)] \varphi^{-1}=[\operatorname{Ker}(\sigma)] \\
& \varphi \beta_{g} \varphi^{-1}=\beta_{\gamma(g)}^{\prime},
\end{aligned} \quad g \in G .
$$

Here, $\operatorname{Aut}(G)$ means the set of all group automorphisms of $G$. We note that the transformation $\varphi$ is in $[\mathcal{S}]$. After preparing several lemmas, we will show the proposition.

As both of the $\sigma$ and $\sigma^{\prime}$ are index cocycles of $\mathcal{S} \subset \mathcal{R}$, it is known ([3]) that they are cohomologous, that is, there exists a measurable function $x \in X \mapsto v(x) \in$ $\Sigma_{N}$ satisfying

$$
\sigma^{\prime}(x, y)=v(x) \sigma(x, y) v(y)^{-1}, \quad \text { a.e. }(x, y) \in \mathcal{R}
$$

Lemma 4.4. There exist an element $\zeta$ in $\Sigma_{N}$, a group automorphism $\gamma$ in $\operatorname{Aut}(G) \cap \operatorname{Aut}(H)$, Rohlin sets $F$ and $F^{\prime}$ of the action $\beta_{G}$ and $\beta_{G^{\prime}}^{\prime}$ respectively with
their intersection of positive measure and a subset $E$ of $F \cap F^{\prime}$ of positive measure such that

$$
\begin{array}{ll}
\left.\operatorname{Ker}(\sigma)\right|_{E}=\left.\operatorname{Ker}\left(\sigma^{\prime}\right)\right|_{E} & \\
v(x)=\zeta, & \forall x \in E \\
\theta_{\gamma(g)}^{\prime}=\zeta \cdot \theta_{g} \cdot \zeta^{-1}, & \forall g \in G
\end{array}
$$

Here $N=[\mathcal{R}: \mathcal{S}]$.
Proof. Since $\sigma\left(\beta_{g} x, x\right)$ is constant a.e., the cocycle property of $\sigma$ implies that the map $g \in G \mapsto \theta_{g} \in \Sigma_{N}$ is a homomorphism, and $\beta_{G} \subset N[\operatorname{Ker}(\sigma)]$. Moreover, since $\beta_{G}$ is outer, the map $g \in G \mapsto \theta_{g} \in \Sigma_{N}$ is a group isomorphism. Since $\beta_{G}$ and $\beta_{G^{\prime}}^{\prime}$ are free respectively, we can obtain Rohlin sets $F$ and $F^{\prime}$ for each so that the set $F \cap F^{\prime}$ is of positive measure. We may choose and fix an element $\zeta$ in $\Sigma_{N}$ such that

$$
m\left\{x \in F \cap F^{\prime} \mid v(x)=\zeta\right\}>0
$$

and set $E=\left\{x \in F \cap F^{\prime} \mid v(x)=\zeta\right\}$. Applying Lemma 3.12 for the index cocycles $\sigma$ and $\sigma^{\prime}$ with ergodic kernels, we see that

$$
\begin{array}{ll}
\mathbf{r}^{\sigma}(\mathcal{R})=\theta_{G}, & \mathbf{r}^{\sigma}(\mathcal{R})=\theta_{H} \\
\mathbf{r}^{\sigma^{\prime}}(\mathcal{R})=\theta_{G}^{\prime}, & \mathbf{r}^{\sigma^{\prime}}(\mathcal{R})=\theta_{H}^{\prime}
\end{array}
$$

Here, we use the symbol $\mathbf{r}^{\sigma}(\mathcal{R})$ etc, instead of $\mathbf{r}(\mathcal{R})$, because we need to show the dependence of the ratio sets on the choice of index cocycles. We note that if $x, y \in E$ then $\sigma^{\prime}(x, y)=\zeta \sigma(x, y) \zeta^{-1}$ a.e. $(x, y) \in \mathcal{R}$. So, for such a point $(x, y)$ in $\mathcal{R}$

$$
\sigma^{\prime}(x, y)=e \Leftrightarrow \sigma(x, y)=e
$$

Lemma 2.2 says that the index ratio set $\left\{\mathbf{r}^{\sigma}(\mathcal{R}), \mathbf{r}^{\sigma}(\mathcal{S})\right\}$ is the pair of the image of $\sigma(x, y)$ for a.e. $(x, y) \in \mathcal{R}$ with $x, y \in E$ and the image of $\sigma(x, y)$ for a.e. $(x, y) \in \mathcal{S}$ with $x, y \in E$. Therefore,

$$
\theta_{G^{\prime}}^{\prime}=\zeta \cdot \theta_{G} \cdot \zeta^{-1}, \quad \theta_{H^{\prime}}^{\prime}=\zeta \cdot \theta_{H} \cdot \zeta^{-1}
$$

So, we can define $\gamma(g) \in G^{\prime}, g \in G$, by

$$
\theta_{g}^{\prime}=\zeta \theta_{\gamma(g)} \zeta^{-1}
$$

Then, we easily see that $\gamma \in \operatorname{Aut}(G) \cap \operatorname{Aut}(H)$.

Since $\operatorname{Ker}(\sigma)$ and $\operatorname{Ker}\left(\sigma^{\prime}\right)$ ergodically act respectively, we can construct finite partitions $\left\{E_{i} \mid i \in \Lambda\right\}$ of $F$ and $\left\{E_{i}^{\prime} \mid i \in \Lambda\right\}$ of $F^{\prime}$ and $e_{i, j} \in[\operatorname{Ker}(\sigma)]_{*}$ and $e_{i, j}^{\prime} \in\left[\operatorname{Ker}\left(\sigma^{\prime}\right)\right]_{*}, i, j \in \Lambda$, satisfying

$$
\begin{aligned}
& E_{0}=E_{0}^{\prime}=E, \\
& E_{i}=\operatorname{Dom}\left(e_{j, i}\right)=\operatorname{Im}\left(e_{i, j}\right), \quad E_{i}^{\prime}=\operatorname{Dom}\left(e_{j, i}^{\prime}\right)=\operatorname{Im}\left(e_{i, j}^{\prime}\right), \\
& e_{i, j} e_{j, k}=e_{i, k}
\end{aligned}
$$

where $F, F^{\prime}$ and $E$ are the sets in Lemma 4.4 and $0 \in \Lambda$ is the specified index.
We define the invertible non-singular transformation $\varphi$ by

$$
\begin{array}{ll}
\varphi x=x, & x \in E, \\
\varphi e_{j, 0} x=e_{j, 0}^{\prime} \varphi x, & x \in E, j \in \Lambda \\
\varphi \beta_{g} x=\beta_{\gamma(g)}^{\prime} \varphi x, & x \in F, g \in G
\end{array}
$$

Then,

$$
\begin{array}{ll}
\varphi\left(E_{i}\right)=E_{i}^{\prime}, & i \in \Lambda \\
\varphi \beta_{g} \varphi^{-1}=\beta_{\gamma(g)}, & g \in G \\
\varphi \beta_{g}(F)=\beta_{\gamma(g)}^{\prime}(F), & g \in G
\end{array}
$$

Proof of Proposition 4.3. The fact that $\varphi \beta_{g} \varphi^{-1}=\beta_{\gamma(g)}^{\prime}, g \in G$ is obvious. Let $g \in G, x \in E_{0}$ and $y \in \beta_{g}(F)$ and assume $(x, y) \in \operatorname{Ker}(\sigma)$. Set $z=\beta_{g}^{-1} y$ and let $i \in \Lambda$ be such that $z \in E_{i}$. Set $x^{\prime}=\varphi x, y^{\prime}=\varphi y$ and $u=e_{0, i} z \in E$ and $u^{\prime}=\varphi u$. Here, $E$ is the set $E$ in Lemma 4.4 and we take the $\zeta \in \Sigma$ in Lemma 4.4. Then,

$$
\begin{aligned}
\sigma^{\prime}\left(y^{\prime}, x^{\prime}\right) & =\sigma^{\prime}\left(y^{\prime}, z^{\prime}\right) \sigma^{\prime}\left(z^{\prime}, x^{\prime}\right)=\theta_{\gamma(g)}^{\prime} \sigma^{\prime}\left(z^{\prime}, u^{\prime}\right) \sigma\left(u^{\prime}, x^{\prime}\right) \\
& =\theta_{\gamma(g)}^{\prime} v\left(u^{\prime}\right) \sigma\left(u^{\prime}, x^{\prime}\right) v\left(x^{\prime}\right)^{-1}=\theta_{\gamma(g)}^{\prime} \zeta \sigma(u, x) \zeta^{-1}
\end{aligned}
$$

and

$$
\sigma(u, x)=\sigma(u, z) \sigma(z, y) \sigma(y, x)=\theta_{g^{-1}}
$$

Hence,

$$
\sigma^{\prime}\left(y^{\prime}, x^{\prime}\right)=\theta_{\gamma(g)}^{\prime} \zeta \theta_{g^{-1}} \zeta^{-1}=\theta_{\gamma(g) \gamma\left(g^{-1}\right)}^{\prime}=e
$$

that is $\left(y^{\prime}, x^{\prime}\right)=(\varphi y, \varphi x) \in \operatorname{Ker}\left(\sigma^{\prime}\right)$. Next consider the case that $x \in E_{i}, y \in$ $\alpha_{g}(F)$. Assume $(x, y) \in \operatorname{Ker}(\sigma)$. Set $x_{0}=e_{0, i} x$, then $\left(x_{0}, y\right) \in \operatorname{Ker}(\sigma)$ and $x_{0} \in E$. So, $\left(\varphi x_{0}, \varphi y\right) \in \operatorname{Ker}\left(\sigma^{\prime}\right)$. By the definition of $\varphi, \varphi x=e_{i, 0}^{\prime} \varphi x_{0}$. Hence, $(\varphi x, \varphi y) \in \operatorname{Ker}\left(\sigma^{\prime}\right)$.

In the general case, let $x \in \beta_{g}(F), y \in \beta_{f}(F)$ and assume $(x, y) \in \operatorname{Ker}(\sigma)$. Set $s=\beta_{g}^{-1} y$ and $t=\beta_{g}^{-1} x \in F$. Then $\sigma(s, t)=\sigma\left(s, \beta_{g} s\right) \sigma(y, x) \sigma\left(\beta_{g} t, t\right)=e$. By the previous argument we see that $(\varphi s, \varphi t) \in \operatorname{Ker}\left(\sigma^{\prime}\right)$. Thus, $(\varphi y, \varphi x)=$ $\left(\beta_{\gamma(g)}^{\prime} \varphi s, \beta_{\gamma(g)}^{\prime} \varphi t\right) \in \operatorname{Ker}\left(\sigma^{\prime}\right)$.

Proof of Theorem 4.1. Combining Theorem 3.1, Proposition 4.2 and Proposition 4.3 , we immediately have Theorem 4.1.

Thus we proved that if an ergodic subrelation $\mathcal{S}$ of an ergodic measured discrete equivalence relation $\mathcal{R}$ has a finite index then the pair $(\mathcal{R}, \mathcal{S})$ admits the uniquely determined system $\left\{\mathcal{P}, H \subset G, \alpha_{G}\right\}$ satisfying the conditions (i), (ii) and (iii) in Theorem 4.1. We call this system the canonical system for $\mathcal{S} \subset \mathcal{R}$.

Next we will show a generalization of Dye's theorem on orbit equivalence of finite measure preserving tranformations to orbit equivalence of pairs of an amenable ergodic measured discrete type $\mathrm{II}_{1}$ equivalence relation and an ergodic subrelation of finite index.

Definition 4.5. (i) A tower $\xi=\left(\mathcal{P}_{\xi}, \mathcal{T}_{\xi}\right)$ on a measurable subset $E \subset X$ consists of a finite partition $\mathcal{P}_{\xi}=\left\{E_{i} \mid i \in \Lambda\right\}$ of $E$, and a finite family of partial transformations $\mathcal{T}_{\xi}=\left\{e_{i, j} \mid i, j \in \Lambda\right\} \subset[\mathcal{R}]_{*}$ satisfying

$$
\begin{array}{ll}
\operatorname{Dom}\left(e_{i, j}\right)=E_{j}, & \operatorname{Im}\left(e_{i, j}\right)=E_{i} \\
e_{i, j} \cdot e_{j, k}=e_{i, k}, & e_{i, i}=\left.\operatorname{Id}\right|_{E_{i}} .
\end{array}
$$

The tower $\xi$ is also considered as the finite subrelation $\left\{\left(e_{i, j} x, x\right) \mid x \in E_{j}, i, j \in \Lambda\right\}$ on $E$. We simply write $\xi=\left\{e_{i, j} \mid i, j \in \Lambda\right\}$.
(ii) Let $\xi_{i}, i=1,2$ be towers on a measurable subset $E$, and let $\mathcal{P}_{\xi_{i}}=\left\{E_{\alpha} \mid\right.$ $\left.\alpha \in \Lambda_{i}\right\}$ and $\mathcal{I}_{\xi_{i}}=\left\{e_{\alpha, \beta} \mid \alpha, \beta \in \Lambda_{i}\right\}$. We say that $\xi_{2}$ refines $\xi_{1}$ if

$$
\begin{array}{ll}
\Lambda_{2}=\Lambda_{1} \rtimes \Gamma, & (\text { ( a finite set }), \\
E_{\alpha}=\bigcup_{\gamma \in \Gamma} E_{(\alpha, \gamma)}, & \left(\alpha \in \Lambda_{1}\right) \text { and }, \\
e_{(\alpha, \gamma),(\beta, \gamma)}=e_{\alpha, \beta} \text { on } E_{(\beta, \gamma)}, & \left(\alpha, \beta \in \Lambda_{1}, \gamma \in \Gamma\right)
\end{array}
$$

Choose and fix an $\alpha \in \Lambda_{1}$, and define the tower $\eta=\left(\mathcal{P}_{\eta}, \mathcal{T}_{\eta}\right)$ on $E_{\alpha}$ by setting

$$
\mathcal{P}_{\eta}=\left\{E_{(\alpha, \gamma)} \mid \gamma \in \Gamma\right\}, \quad \mathcal{T}_{\eta}=\left\{e_{(\alpha, \gamma),\left(\alpha, \gamma^{\prime}\right)} \mid \gamma, \gamma^{\prime} \in \Gamma\right\}
$$

then we denote $\xi_{2}$ by $\xi_{1} \rtimes \eta$ and call it a product tower.
Theorem 4.6. The mapping $\{(\mathcal{R}, \mathcal{S}) \mid \mathcal{R}$ an ergodic measured discrete amenable type $\mathrm{II}_{1}$ equivalence relation and $\mathcal{S}$ an ergodic subrelation of finite index $\}$ $\ni(\mathcal{R}, \mathcal{S}) \rightarrow(\mathbf{r}(\mathcal{R}), \mathbf{r}(\mathcal{S})) \in\{(G, H) \mid G$ a finite group and $H$ a subgroup which does not contain any normal subgroup $\neq\{e\}$ of $G\}$ is a bijection up to orbit equivalence and conjugacy of a group and a subgroup.

Proof. First of all we note that Theorem 3.1 shows that the mapping defined as above is well defined up to orbit equivalence and conjugacy of a group and a
subgroup. Next we show the mapping is surjective. So, we let $G, H$ be a finite group and a subgroup which does not contain any normal subgroup $\neq\{e\}$ of $G$. Set

$$
Y=\prod_{n=-\infty}^{\infty} G
$$

where $Y$ is equipped with the infinite product measure of the uniform measure on each coordinate space $G$. On $Y$ the left shift mapping is defined in a measure preserving way. We denote it by $S$. Then we construct the product space $X=Y \rtimes G$ equipped with the product measure whose second coordinate marginal measure is the uniform measure of $G$. We then define a skew product measure preserving transformation $T$ on $X$ by setting for $y=\left(y_{n}\right) \in Y$ and $g \in G$

$$
T(y, g)=\left(S y, y_{0} \cdot g\right)
$$

We also define a $G$-action $\alpha_{G}$ on $X$ by

$$
\alpha_{l}(y, g)=\left(y, g \cdot l^{-1}\right), \quad l \in G
$$

We let $\mathcal{R}$ (respective $\mathcal{S}$ ) be the equivalence relation generated by $T$ and $\alpha_{l}$ 's, $l \in G$ (respectively $T$ and $\alpha_{l}$ 's, $l \in H$ ). Since the action $\alpha_{G}$ commutes with $T, \mathcal{R}$ is an amenable equivalence relation. Since the left shift mapping is ergodic, thus we have a pair of an ergodic measured discrete amenable type $\mathrm{II}_{1}$ equivalence relation $\mathcal{R}$ and an ergodic subrelation $\mathcal{S}$.

If we let $\mathcal{P}$ be the equivalence relation generated by $T$, then it is easily seen that $\left\{\mathcal{P}, H \subset G, \alpha_{G}\right\}$ gives the canonical system for the inclusion $\mathcal{R} \supset \mathcal{S}$ and that

$$
(\mathbf{r}(\mathcal{R}), \mathbf{r}(\mathcal{S}))=(G, H)
$$

Finally, we show the injectivity of our mapping up to orbit equivalence and conjugacy of a group and a subgroup. We are given inclusions $\mathcal{R} \supset \mathcal{S}$ on $(X, \mathcal{B}, m)$ and $\mathcal{R}^{\prime} \supset \mathcal{S}^{\prime}$ on $\left(X^{\prime}, \mathcal{B}^{\prime}, m^{\prime}\right)$ which are orbit equivalent. As usual we denote their canonical systems by $\left\{\mathcal{P}, H \subset G, \alpha_{G}\right\}$ and $\left\{\mathcal{P}^{\prime}, H^{\prime} \subset G^{\prime}, \alpha_{G^{\prime}}^{\prime}\right\}$. We may assume that $G=G^{\prime}, H=H^{\prime}$ and that $m$ (respective $m^{\prime}$ ) is $\mathcal{R}=\mathcal{P} \rtimes_{\alpha} G$-invariant (respective $\mathcal{R}^{\prime}=\mathcal{P}^{\prime} \rtimes_{\alpha^{\prime}} G$-invariant) probability measure.

Firstly, we take a $\mathcal{P} \rtimes_{\alpha} G$-tower $\left\{e_{i, j} \mid i, j \in \Lambda\right\}$ of the set $X$. We put

$$
E_{j}=\operatorname{Dom}\left(e_{i, j}\right)
$$

Corresponding to this tower, we choose a finite partition $\left\{E_{i}^{\prime} \mid i \in \Lambda\right\}$ of $X^{\prime}$ of equal measure.

We are going to show that for an arbitrary fixed index $i_{0} \in \Lambda$ and for any measure preserving isomorphism $\varphi: E_{i_{0}} \rightarrow E_{i_{0}}^{\prime}$, there exists a $\mathcal{P} \rtimes_{\alpha} G$-tower $\left\{e_{i, j}^{\prime} \mid\right.$ $i, j \in \Lambda\}$ of the set $X^{\prime}$ and an extended invertible measure preserving map $\varphi$ : $X \rightarrow X^{\prime}$ such that

$$
\begin{aligned}
& \operatorname{Dom}\left(e_{i, j}^{\prime}\right)=E_{j}^{\prime}, \quad \operatorname{Im}\left(e_{i, j}^{\prime}\right)=E_{i}^{\prime}, \quad \varphi \cdot e_{i, j}(x)=e_{i, j}^{\prime} \cdot \varphi(x), \quad\left(x \in E_{j}\right) \\
& \left.\left.\alpha_{g} \cdot e_{i, j} \cdot \operatorname{Id}\right|_{A} \in[\mathcal{P}]_{*} \Leftrightarrow \alpha_{g}^{\prime} \cdot e_{i, j}^{\prime} \cdot \operatorname{Id}\right|_{\varphi(A)} \in\left[\mathcal{P}^{\prime}\right]_{*}
\end{aligned}
$$

where $A \subset E_{j}$ and $g \in G$. We note that if $\left.\alpha_{g} \cdot e_{i, j} \cdot \mathrm{Id}\right|_{A} \in[\mathcal{P}]_{*}$ then $g$ is uniquely determined.

Each $e_{j, i_{0}}$ is of the form :

$$
e_{j, i_{0}} x=\alpha_{g} \cdot \gamma x, \quad\left(x \in E_{i_{0}}\right)
$$

where $\gamma \in[\mathcal{P}]_{*}$ with $\operatorname{Dom}(\gamma)=E_{i_{0}}$, and $g=g(x, j) \in G$. As if necessary one can decompose the set $E_{i_{0}}$ into at most countable number of disjoint sets on which $g(x, j)$ is constant, we may and do assume that $g(x, j)$ is a function of only $j$ and write

$$
g(j)=g(x, j), \quad\left(x \in E_{i_{0}}\right)
$$

Since $m^{\prime}\left(E_{i_{0}}^{\prime}\right)=m\left(E_{i_{0}}\right)$, we have a $m-m^{\prime}$ preserving isomorphism $\varphi: E_{i_{0}} \rightarrow$ $E_{i_{0}}^{\prime}$. We note

$$
m^{\prime}\left(\alpha_{g(j)}^{\prime}\left(E_{i_{0}}^{\prime}\right)\right)=m^{\prime}\left(E_{j}^{\prime}\right)
$$

So, using Hopf-equivalence by $\mathcal{P}^{\prime}$, we obtain $h_{j}^{\prime} \in\left[\mathcal{P}^{\prime}\right]_{*}$ such that

$$
\left\{\begin{array}{l}
\operatorname{Dom}\left(h_{j}^{\prime}\right)=\alpha_{g(j)}^{\prime}\left(E_{i_{0}}^{\prime}\right), \\
\operatorname{Im}\left(h_{j}^{\prime}\right)=E_{j}^{\prime} .
\end{array}\right.
$$

These partial transformations $h_{j}^{\prime}$ give us partial transformations $e_{j, i_{0}}^{\prime}: E_{i_{0}}^{\prime} \rightarrow E_{j}^{\prime}$ by setting

$$
e_{j, i_{0}}^{\prime} x^{\prime}=h_{j}^{\prime} \cdot \alpha_{g(j)}^{\prime} x^{\prime}, \quad\left(x^{\prime} \in E_{i_{0}}^{\prime}\right)
$$

Then,

$$
\left\{\begin{array}{l}
e_{j, i_{0}}^{\prime} \in\left[\mathcal{P}^{\prime} \rtimes_{\alpha^{\prime}} G\right]_{*} \\
\operatorname{Dom}\left(e_{j, i_{0}}^{\prime}\right)=E_{i_{0}}^{\prime} \\
\operatorname{Im}\left(e_{j, i_{0}}^{\prime}\right)=E_{j}^{\prime} \\
\left.\left.\alpha_{g} \cdot e_{j, i_{0}} \cdot \operatorname{Id}\right|_{A} \in\left[\mathcal{P}_{m}\right]_{*} \Leftrightarrow \alpha_{g}^{\prime} \cdot e_{j, i_{0}}^{\prime} \cdot \operatorname{Id}\right|_{\varphi(A)} \in\left[\mathcal{P}^{\prime}{ }_{m^{\prime}}\right]_{*},
\end{array}\right.
$$

where $A \subset E_{i_{0}}$ and $g \in G$. We note that

$$
e_{j, i_{0}} \in\left[\mathcal{P} \rtimes_{\alpha} H\right]_{*} \Leftrightarrow g(j) \in H \Leftrightarrow e_{j, i_{0}}^{\prime} \in\left[\mathcal{P}^{\prime} \rtimes_{\alpha^{\prime}} H\right]_{*}
$$

Now let us extend $\varphi$ to a $m-m^{\prime}$ preserving measure isomorphism $X \rightarrow X^{\prime}$ by setting for each $j$

$$
\varphi x=e_{j, i_{0}}^{\prime} \cdot \varphi \cdot e_{i_{0}, j} x \quad\left(x \in E_{j}\right)
$$

Set

$$
\left\{\begin{array}{l}
e_{i_{0}, j}^{\prime}=e_{j, i_{0}}^{\prime}-1 \\
e_{j, l}^{\prime}=e_{j, i_{0}}^{\prime} \cdot e_{i_{0}, l}^{\prime} \\
\xi^{\prime}=\left\{e_{j, l}^{\prime} \mid j, l \in \Lambda\right\}
\end{array}\right.
$$

Thus we have constructed the desired $\mathcal{P}^{\prime} \rtimes_{\alpha^{\prime}} G$-tower $\xi^{\prime}=\left\{e_{i, j}^{\prime} \mid i, j \in \Lambda\right\}$ of the set $X^{\prime}$.

We take a $\mathcal{P}^{\prime} \rtimes_{\alpha^{\prime}} G$-tower $\eta^{\prime}$ of the set $E_{i_{0}}^{\prime}$ such that the product tower $\xi^{\prime} \rtimes \eta^{\prime}$ approximates $\mathcal{R}^{\prime}$-orbits and the measurable subsets of $X^{\prime}$ in some fixed precision. Again take a corresponding partition of the set $E_{i_{0}}$ and copy the tower $\eta^{\prime}$ into this set in the same way as previous argument. Apply again this procedure and contiune back and forth in this fashion. In the limit we obtain a $m-m^{\prime}$ preserving measure isomorphism $\varphi: X \rightarrow X^{\prime}$ satisfying that for a.e. $x$,

$$
\left\{\begin{array}{l}
\varphi\left(\mathcal{P} \rtimes_{\alpha} G(x)\right)=\mathcal{P}^{\prime} \rtimes_{\alpha^{\prime}} G(\varphi(x)) \\
\varphi\left(\mathcal{P} \rtimes_{\alpha} H(x)\right)=\mathcal{P}^{\prime} \rtimes_{\alpha^{\prime}} H(\varphi(x)) .
\end{array}\right.
$$

## 5. COMPUTATION OF INDEX RATIO SETS

Let us take a finite-to-one factor map $\varphi$ from an ergodic finite measure preserving transformation $T$ on a Lebesgue measure space $\left(X, \mathfrak{B}_{X}, m_{X}\right)$ to an ergodic finite measure preserving transformation $S$ on a Lebesgue measure space $\left(Y, \mathfrak{B}_{Y}, m_{X}\right)$, that is, $\pi T=S \pi, \pi^{-1}\left(\mathfrak{B}_{Y}\right) \subset \mathfrak{B}_{X}, m_{X}\left(\pi^{-1} \cdot\right)=m_{Y}(\cdot)$. By $\mathcal{S}$, we denote the ergodic measured discrete equivalence relation $\left\{\left(T^{n} x, x\right) \mid n \in \mathbb{Z}\right.$, $x \in X\}$. Let us define an ergodic equivalence relation $\mathcal{R}$ by

$$
\mathcal{R}=\mathcal{S}_{X} \vee\left\{\left(x, x^{\prime}\right) \mid \pi(x)=\pi\left(x^{\prime}\right)\right\}
$$

Here, the right hand side means the equivalence relation generated by both of the relation $\mathcal{S}$ and $\left\{\left(x, x^{\prime}\right) \mid \pi(x)=\pi\left(x^{\prime}\right)\right\}$. We remark that $\mathcal{R}$ is amenable. Under this setup, we are going to show a computation of the pair of index ratio sets of
$\mathcal{S} \subset \mathcal{R}$, when the factor map is arising from a sofic system. For this, let us take the following labeled graph:


Construct the set $X$ of all possible two sided infinite concatenation of edges and the set $Y$ of all possible two sided infinite concatenation of labels respectively. Shifts $T$ on $X$ and $S$ on $Y$ are called a topological Markov shift and a sofic system respectively. A natural map from $\left(x_{n}\right)_{n \in \mathbb{Z}} \in X$ to $\left(y_{n}\right)_{n \in \mathbb{Z}} \in Y$ is induced by defining that each $y_{n}$ is the label of an edge $x_{n}$. Introducing the maximal measures $m$ for $T$ and $\mu$ for $S$ respectively, we obtain a measure preserving factor map between $T$ and $S$ (i.e. $\pi \cdot T=S \cdot \pi$ ). We notice that since the directed graph is irreducible, both of $T$ and $S$ are ergodic and that they have the unique maximal measures, because the directed graph is aperiodic.

Define the permutations $\varphi_{a}, \varphi_{b}, \varphi_{c} \in \Sigma_{3}$ acting on the set $\{0,1,2\}$ by

$$
\varphi_{c}=\left(\begin{array}{lll}
0 & 1 & 2
\end{array}\right), \quad \varphi_{b}=\left(\begin{array}{lll}
1 & 0 & 2
\end{array}\right), \quad \varphi_{a}=\left(\begin{array}{lll}
1 & 2 & 0
\end{array}\right) .
$$

Every path $x=\left(x_{n}\right)_{n \in \mathbb{Z}} \in X$ is identified with $(y, i) \in Y \times\{0,1,2\}$, where $y=\left(y_{n}\right)_{n \in \mathbb{Z}}$ and $i$ the initial vertex of the edge $x_{0}$ and $y_{n}$ is the label of $x_{n}$. So, we may and do assume $X=Y \times\{0,1,2\}$. Through this identification, $T$ is of the form $T(y, i)=\left(S y, \varphi_{y_{0}}(i)\right),(y, i) \in X$. The maximal measures $m_{X}$ and $m_{Y}$ are given by

$$
\begin{array}{ll}
m_{X}=m_{Y} \times \mu, & \mu(0)=\mu(1)=\mu(2)=\frac{1}{3} \\
m_{Y}=\prod_{i=1}^{\infty} P, & P(a)=P(b)=P(c)=\frac{1}{3}
\end{array}
$$

Set

$$
\begin{array}{ll}
\varphi(n, y)=\varphi_{y_{n-1}} \cdots \varphi_{y_{1}} \cdot \varphi_{y_{0}}, & n>0 \\
\varphi(0, y)=\mathrm{id} \\
\varphi(n, y)=\varphi_{y_{n}}^{-1} \cdots \varphi_{y_{-2}}^{-1} \cdot \varphi_{y_{-1}}^{-1}, & n<0
\end{array}
$$

The $\varphi$ is a cocycle of $T$ and satisfies $T^{n}(y, i)=\left(S^{n} y, \varphi(n, y)(i)\right)$.
Define the transformation $\psi$ by $\psi(y, i)=(y, i+1(\bmod 3)),(y, i) \in X, n \in \mathbb{Z}$. Then we easily see that $\left\{\mathrm{id}, \psi, \psi^{2}\right\}$ is the set of choice functions of $\mathcal{S} \subset \mathcal{R}$. Here we notice $[\mathcal{R}: \mathcal{S}]=3$.

By $\sigma$, we denote the index cocycle corresponding to the above choice functions, that is, if $i, j \in\{0,1,2\}$ and $\left((y, k),\left(y^{\prime}, k^{\prime}\right)\right) \in \mathcal{R}$ then

$$
j=\sigma\left(\left(y^{\prime}, k^{\prime}\right),(y, k)\right)(i) \quad \text { if and only if } \quad\left(\left(y^{\prime}, k^{\prime}+j\right),((y, k+i)) \in \mathcal{S}\right.
$$

Lemma 5.1. The restriction $\left.\operatorname{Ker}(\sigma)\right|_{Y \times\{0\}}$ of the subrelation $\operatorname{Ker}(\sigma)$ to the set $Y \times\{0\}$ is ergodic.

Proof. Set $X_{1}=X \times\{0,1,2\}=Y \times\{0,1,2\} \times\{0,1,2\}$, and define the measure preserving transformation $T_{1}$ on $X_{1}$ by

$$
T_{1}(y, i, j)=\left(S y, \varphi_{y_{0}}(i), \varphi_{y_{0}}(j)\right), \quad(y, i, j) \in X_{1}
$$

Later, we will show that the number of the ergodic components of $T_{1}$ is 2 . If so, one of them is the subset $Y \times\{(i, j) \mid i \neq j\} \subset X_{1}$, and hence the induced transformation of $T_{1}$ to the subset $Y \times\{0\} \times\{1\}$ is ergodic, too. Take any measurable subsets $E, F \subset Y$ of positive measure. Then, there exist $k, l \in \mathbb{Z}$ and subsets $E_{0} \subset E, F_{0} \subset F$ of positive measure satisfying

$$
\begin{aligned}
& \left.T_{1}\right|_{Y \times\{0\} \times\{1\}} ^{k}(y, 0,1)=\left(S^{l} y, \varphi(l, y)(0), \varphi(l, y)(1)\right), \quad y \in E_{0} \\
& S^{l}\left(E_{0}\right)=F_{0}
\end{aligned}
$$

Hence,

$$
\sigma\left(\left(S^{l} y, 0\right),(y, 0)\right)(0)=0, \quad \sigma\left(\left(S^{l} y, 0\right),(y, 0)\right)(1)=1
$$

That is, $\left(\left(S^{l} y, 0\right),(y, 0)\right) \in \operatorname{Ker}(\sigma), y \in E_{0}$. Moreover, $T^{l}\left(E_{0} \times\{0\}\right)=F_{0} \times\{0\}$ and $\left.\operatorname{Ker}(\sigma)\right|_{Y \times\{0\}}$ is ergodic.

To see that $T_{1}$ has only two ergodic components, we consider the following
labeled graph.
c

|  | $b$ |  |
| :--- | :--- | :--- |
|  |  | 10 |

c

02

12
c
$a \quad a$
$b$
b
b
$b$

## c

21
$a$

$11 c$
$a$
$a$
22
$b \quad c$

| $b$ | 11 | $c$ |
| :--- | :--- | :--- |
| $b$ |  |  |

c
a
a
c

In fact, the natural map obtained from this labeled graph which has two irreducible components, is the factor map $\pi_{1}$ from $T_{1}$ to $S$, that is, $\pi_{1}(y, i, j)=y$. So, the ergodic components of $T_{1}$ are these two disjoint path spaces consisting of infinite concatenation of edges arising from each irreducible component.

Lemma 5.2. The index ratio set of the $\{\mathcal{R}, \mathcal{S}\}$ is

$$
\{\mathbf{r}(\mathcal{R}), \mathbf{r}(\mathcal{S})\}=\left\{\Sigma_{3}, \Sigma_{2}\right\}
$$

Proof. We saw that $\left.\operatorname{Ker}(\sigma)\right|_{Y \times\{0\}}$ is ergodic. So, by Lemma 2.3, it is enough to compute the images $\{\sigma(x, z) \mid x, z \in Y \times\{0\},(x, z) \in \mathcal{R}\}$ and $\{\sigma(x, z) \mid x, z \in$ $Y \times\{0\},(x, z) \in \mathcal{S}\}$. If $((y, 0),(u, 0)) \in \mathcal{S}$, then $\varphi(n, y)(0)=0$, where $u=S^{n} y$. In this case, we see from the above figure that $\varphi(n, y)(1) \in\{1,2\}$, and both of the cases occur. In other words,

$$
\sigma((u, 0),(y, 0))=\left(\begin{array}{lll}
0 & 1 & 2
\end{array}\right)
$$

or,

$$
\sigma((u, 0),(y, 0))=(021)
$$

Thus, we showed $\mathbf{r}(\mathcal{S})=\Sigma_{2}$. In order to prove $\mathbf{r}(\mathcal{R})=\Sigma_{3}$, it is enough to show that there is a permutation in $\mathbf{r}(\mathcal{R})$ which does not belong to $\Sigma_{2}$. In fact,

$$
\sigma((S y, 0),(y, 0))=(120), \quad \text { if } y_{0}=a
$$

Because, if $y \in Y$ satisfies $y_{0}=a$ then

$$
\begin{array}{ll}
((y, 0),(y, 1)) \in \mathcal{R},((y, 1), & (T(y, 1))=((y, 1),(S y, 2)) \in \mathcal{S} \\
((y, 0), T(y, 0))=(y, 0), & (S y, 1)) \in \mathcal{S} .
\end{array}
$$

Hence, $(1,2,0) \in \mathbf{r}(\mathcal{R})$.
Remark 5.3. In amenable type $\mathrm{II}_{1}$ case, the orbit equivalence classes of relations-subrelations of index 3 are only two. In fact by Theorem 4.6, all possible index ratio sets are the pairs $\left\{\mathbb{Z}_{3},\{e\}\right\}$ and $\left\{\Sigma_{3}, \Sigma_{2}\right\}$. The first case appears in the previous example. About the second case, for instance it is enough to consider the following labeled graph.


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