

ON MULTIDIMENSIONAL SINGULAR INTEGRAL OPERATORS. II: THE CASE OF COMPACT MANIFOLDS

ROLAND DUDUCHAVA

INTRODUCTION

Singular integral operators (equations)

$$(0.1) \quad A\varphi(x) \equiv a(x)\varphi(x) + \int\limits_u \frac{\Omega(x, x-y)}{|x-y|^n} \varphi(y) dy = f(x), \quad x \in M$$

are investigated, where M is a compact manifold with the boundary $\partial M \neq \emptyset$; $f(x) \in (H^{sp})^N(M)$, $\varphi \in (H_0^{sp})^N(M)$, $1 < p < \infty$, $-\infty < s < \infty$; proofs here are based on [3], where the first part of the present investigations (the half-space case $M = \mathbf{R}^{n+}$) was published.

As it was already mentioned in [3] the operators (0.1) were investigated by Simonenko [6] (the case $p = 2$, $s = 0$) and by Wišik and Eskin [7] (the case $p = 2$, $-\infty < s < \infty$).

The main tool of investigation here is the local principle (cf. § 3.2^c), which is a slight modification of the local principle from [5] (cf. § 1.6), extended with some notions from [6].

We set forth here the numeration of sections; thus the references to §§ 1–2 will mean the reference to [3]; all notations from [3] are used without the further explanations.

3. PRELIMINARIES

1°. ON THE ISOMORPHISM OF SOBOLEV-SLOBODECKIJ SPACES. Consider the operators

$$\Lambda_\pm^s \varphi = \mathcal{F}^{-1} g_\pm^s \mathcal{F} \varphi, \quad \Lambda^s \varphi = \mathcal{F}^{-1} g_0^s \mathcal{F} \varphi, \quad \varphi \in C_0^\infty(\mathbf{R}^n), \quad -\infty < s < \infty,$$

where

$$\begin{aligned} g_{\pm}^s(\xi) &= (i\xi_1 \mp i|\xi'| \mp 1)^s, \quad \xi = (\xi_1, \xi') \in \mathbf{R}^n, \\ g_0^s(\xi) &= (1 + |\xi|)^s; \end{aligned}$$

these operators have continuous extensions

$$A^s, A_{\pm}^s : H^{rp}(\mathbf{R}^n) \rightarrow H^{(r-s)p}(\mathbf{R}^n) \quad (-\infty < r < \infty)$$

and these extensions are isomorphisms (A^s arranges even the isometrical isomorphism $\|\varphi\|_{rp} = \|A^s \varphi\|_{(r-s)p}$); obviously

$$A^s A^{-s} = I, \quad A_{\pm}^s A_{\mp}^{-s} = I.$$

The operators

$$\tilde{A}_{\pm}^s = P_{1+} A^s l_{1+},$$

where P_{1+} and l_{1+} are restricting and extending operators, also arrange isomorphisms (cf. [2, 4])

$$\begin{aligned} \tilde{A}_{\pm}^s : H_0^{rp}(\mathbf{R}^{n+}) &\rightarrow H_0^{(r-s)p}(\mathbf{R}^{n+}), \quad \tilde{A}_{\pm}^s \tilde{A}_{\mp}^{-s} = I, \\ \tilde{A}_{-}^s : H^{rp}(\mathbf{R}^{n+}) &\rightarrow H^{(r-s)p}(\mathbf{R}^{n+}), \quad (-\infty < s, r < \infty). \end{aligned}$$

The following two lemmas are easy to prove (cf., for example, [2, 4]).

LEMMA 3.1. *The operator $W_a^0 \in \mathcal{L}((H^{sp})^N(\mathbf{R}^n))$ is isomorphic*

$$W_a^0 = B^{-s} W_a^0 B^s \quad (B^{\pm s} = A^{\pm s}, A_{\pm}^{\pm s}, A_{\mp}^{\pm s})$$

to itself $W_a^0 \in \mathcal{L}(L_p^N(\mathbf{R}^n))$ operating in the space $L_p^N(\mathbf{R}^n)$; therefore $W_a^0 \in \mathcal{L}((H^{sp})^N(\mathbf{R}^n))$ if and only if $a(\xi) \in M_p^{N \times N}(\mathbf{R}^n)$ ($1 < p < \infty$, $-\infty < s < \infty$).

LEMMA 3.2. *The operator*

$$(3.1) \quad W_a^1 \in \mathcal{L}((H_0^{sp})^N(\mathbf{R}^{n+}), (H^{sp})^N(\mathbf{R}^{n+}))$$

is isomorphic

$$W_a^1 = A_{-}^{-s} W_{a_s}^1 A_{+}^s$$

to the operator

$$(3.2) \quad W_{a_s}^1 \in \mathcal{L}(L_p^N(\mathbf{R}^{n+})), \quad a_s(\xi) = \left(\frac{i\xi_1 + i|\xi'| + 1}{i\xi_1 - |\xi'| - 1} \right)^s a(\xi);$$

hence (3.1) is valid if and only if $a(\xi) \in M_p^{N \times N}(\mathbf{R}^n)$.

We remind that $(C_0^r)^{N \times N}(\mathbf{R}^n)$ denotes the set of $N \times N$ matrix-functions with entries $a(\xi) \in C_0^r(\mathbf{R}^n)$ having continuous derivatives $D_{\xi}^k a(\xi)$ ($|k| \leq r$) with compact supports.

LEMMA 3.3. *Let $a(\xi) \in (C_0^r)^{N \times N}(\mathbf{R}^n)$ and $|s| < r$.*

The operators

$$T = \Lambda^{-s} a \Lambda^s - aI, \quad T_{\pm} = \Lambda_{\pm}^{-s} a \Lambda_{\pm}^s - aI,$$

$$\tilde{T}_{\pm} = \tilde{\Lambda}_{\pm}^{-s} a \tilde{\Lambda}_{\pm}^s - aI, \quad T'_{\pm} = \Lambda_{\pm}^{-s} a \Lambda_{\mp}^s - a W_{g_{\pm s}}^0,$$

$$\tilde{T}'_{\pm} = \tilde{\Lambda}_{\pm}^{-s} a \tilde{\Lambda}_{\mp}^s - a W_{g_{\pm s}}^1,$$

where

$$(3.3) \quad g_{\mu}(\xi) = \left(\frac{i\xi_1 + |\xi'|}{i\xi_1 - |\xi'|} \right)^{\mu},$$

are compact

$$T, T_{\pm}, T'_{\pm} \in \mathfrak{S}(L_p^N(\mathbf{R}^n)), \quad \tilde{T}_{\pm}, \tilde{T}'_{\pm} \in \mathfrak{S}(L_p^N(\mathbf{R}^{n+})).$$

Proof. Obviously we can suppose $N = 1$ and due to standard approximation consider only $a \in C_0^\infty(\mathbf{R}^n)$; applying further Theorem 1.11 (namely the second part of it on the interpolation of compact operators) we can concentrate only on the case $p = 2$ (due to the boundedness of operators under the consideration in all L_p spaces).

The inclusion $T \in \mathfrak{S}(L_p(\mathbf{R}^n))$ was proved in [1], Chapter III, § 9. We consider only T'_- , because T'_+, T_{\pm} can be considered similarly and $\tilde{T}'_{\pm} = P_{1+} T'_{\pm} l_{1+}$, $\tilde{T}_{\pm} = P_{1+} T_{\pm} l_{1+}$.

Λ_+^s is a pseudodifferential operator (cf. [1, 4, 7]) and its symbol $(i\xi_1 - |\xi'| - 1)^s$ belongs to the class $S_{1,0}^s(\mathbf{R}^n)$ (cf. [7], Chapter II, § 1); the operator $d\Lambda_+^s - \Lambda_+^s dI$ is also pseudodifferential for all $d \in C_0^\infty(\mathbf{R}^n)$ and its symbol belongs to $S_{1,0}^{s-1}(\mathbf{R}^n)$; hence $d\Lambda_-^s - \Lambda_-^s dI \in \mathcal{L}(H^r(\mathbf{R}^n), H^{r-s+1}(\mathbf{R}^n))$ (here $H^r(\mathbf{R}^r) \stackrel{\text{def}}{=} H^r(\mathbf{R}^n)$; cf. [7], § 6 and [3], § 18).

Let now $b(\xi) \in C_0(\mathbf{R}^n)$ be such that $b(\xi) = 1$ for all $\xi \in \text{supp } a$; then $a(\xi)b(\xi) \equiv a(\xi)$, $a\Lambda_+^s = AK_1 + a\Lambda_+^s bI$, $K_1 = b\Lambda_+^s - \Lambda_+^s bI$; rewrite now T'_- in the form

$$(3.4) \quad \begin{aligned} T'_- &= \Lambda_-^{-s}(aK_1 + K_2 bI) + K_3 aI, \\ K_2 &= a\Lambda_+^s - \Lambda_+^s aI, \quad K_3 = \Lambda_-^{-s}\Lambda_+^s - W_{g_{-s}}^0. \end{aligned}$$

As we already noticed K_1 and K_2 are pseudodifferential operators of order $s-1$ and therefore $K_1, K_2 \in \mathcal{L}(H^s(\mathbf{R}^n), H^1(\mathbf{R}^n))$; but then (cf. [4], Theorem 18.4 and [1], Chapter III, Lemma 8.1)

$$aK_1, K_2 bI \in \mathfrak{S}(H^s(\mathbf{R}^n), L_2(\mathbf{R}^n)),$$

since $\text{supp } a \subset \text{supp } b$ are compact. On the other hand

$$\Lambda_-^{-s} \in \mathcal{L}(L_2(\mathbf{R}^n), H^s(\mathbf{R}^n))$$

and therefore

$$(3.5) \quad A_-^s a K_1, \quad A_-^s K_2 b I \in \mathfrak{S}(L_2(\mathbf{R}^n)).$$

Since

$$A_-^s A_+^s = W_{\tilde{g}_{-s}}^0, \quad \tilde{g}_{-s}(\xi) := \left(\frac{i\xi_1 + |\xi'| + 1}{i\xi_1 - |\xi'| - 1} \right)^{-s};$$

we obtain

$$K_3 = W_{d_{-s}}^0, \quad d_{-s}(\xi) = \tilde{g}_{-s}(\xi) - g_{-s}(\xi);$$

clearly $d_{-s} \in m_2(\mathbf{R}^n)$ and $d_{-s}(\infty) = 0$; Theorem 1.12 yields then

$$(3.6) \quad a K_3 \in \mathfrak{S}(L_2(\mathbf{R}^n));$$

due to (3.4)–(3.6) the desired inclusion $T'_- \in \mathfrak{S}(L_2(\mathbf{R}^n))$ is evident. \square

2°. LOCAL PRINCIPLE. II. We present here a local principle which is a slight modification of the local principles from [5,6] (cf. § 1.6°).

Let X_1, X_2 be the Banach spaces and

$$\mathcal{L}' = \mathcal{L}(X_1, X_2), \quad \mathfrak{S}' = \mathfrak{S}(X_1, X_2),$$

$$\mathcal{L}'' = \mathcal{L}(X_2, X_1), \quad \mathfrak{S}'' = \mathfrak{S}(X_2, X_1);$$

$\tilde{\mathcal{L}'} = \mathcal{L}' / \mathfrak{S}'$ denotes the factor-algebra with the norm

$$\|A\|_{\tilde{\mathcal{L}'}} = \|A\| \stackrel{\text{def}}{=} \inf_{T \in \mathfrak{S}'} \|A + T\|.$$

A set

$$\Delta \subset \mathcal{L}(X_1) \cap \mathcal{L}(X_2)$$

is called a *localizing class* provided

$$\mathfrak{S}(X_1) \cap \mathfrak{S}(X_2) \cap \Delta = \{0\}$$

and for each $A_1, A_2 \in \Delta$ there exists $A \in \Delta$ such that $A_j A = A A_j = A$ ($j = 1, 2$).

Two elements $A, B \in \tilde{\mathcal{L}'}$ are called Δ -equivalent, written $A \sim \Delta B$, provided

$$\inf_{E \in \Delta} \|(A - B)E\| = \inf_{E \in \Delta} \|E(A - B)\| = 0.$$

An element $A \in \tilde{\mathcal{L}'}$ is called *left (right) Δ -regularizable* if there exist $R \in \mathcal{L}''$ and $B \in \Delta$ such that $RAB = B + T$, $T \in \mathfrak{S}(X_1)$ ($BAR = B + T$, $T \in \mathfrak{S}(X_2)$).

A is called Δ -regularizable provided it is left and right Δ -regularizable.

Similarly Δ -invertibility, left and right Δ -invertibility are defined provided $T = 0$ (cf. § 1.6°).

A system $\{\Delta_\omega\}_{\omega \in \Omega}$ of localizing classes is called a *covering* if from each set $\{A_\omega\}_{\omega \in \Omega}$, $A_\omega \in \Delta_\omega$, finite number of elements can be selected $\{A_{\omega_k}\}_{k=1}^l$ such that $A = \sum_{k=1}^l A_{\omega_k}$ has the regularizer

$$RA = I + T_1, \quad AR = I + T_2, \quad T_1, T_2 \in \mathfrak{S}(X_1) \cap \mathfrak{S}(X_2).$$

THEOREM 3.4. Let $\{\Delta_\omega\}_{\omega \in \Omega}$ be a covering system of localizing classes and $A \not\sim B_\omega$ ($A, B_\omega \in \mathcal{L}'$, $\omega \in \Omega$), $AB - BA \in \mathfrak{S}'$ for all $B \in \bigcup_{\omega \in \Omega} \Delta_\omega$.

The operator A is Fredholm (has a left or a right regularizer) if and only if B_ω have Δ_ω -regularizers (B_ω have left, have right Δ_ω -regularizers) for all $\omega \in \Omega$.

Proof is completely similar to the proof of Theorem 1.1 from [5], Chapter XII (cf. Theorem 1.17 above).

Consider now the particular case

$$X_1 = (H_0^{sp})^N(M), \quad X_2 = (H^{sp})^N(M), \quad 1 < p < \infty, \quad -\infty < s < \infty,$$

where M is a r -smooth ($r > s$) n -dimensional compact manifold with the boundary $\partial M \neq \emptyset$; denote

$$(3.7) \quad \begin{aligned} \mathcal{L}_{sp}^N(M) &= \mathcal{L}((H_0^{sp})^N(M), (H^{sp})^N(M)), \\ \mathfrak{S}_{sp}^N(M) &= \mathfrak{S}((H_0^{sp})^N(M), (H^{sp})^N(M)). \end{aligned}$$

Let $x \in M$ and consider

$$(3.8) \quad \Delta_x = \{v_x I : v_x \in C^r(M), v_x(t) = 1 \text{ in some neighborhood of } x \in M\}.$$

Clearly Δ_x is a localizing class in $\mathcal{L}_{sp}^N(M)$ and $\{\Delta_x\}_{x \in M}$ (due to the compactness of M) is a covering.

Clearly

$$\sup_{v_x I \in \Delta_x} \|v_x I\|_{sp} = \infty \quad \text{for } s \neq 0;$$

nevertheless

$$(3.9) \quad \sup_{v_x I \in \Delta_x} |||v_x I|||_{sp} = \sup_{v_x I \in \Delta_x} \inf_{\gamma} \|v_x I + T\|_{sp} < \infty,$$

where the norm is taken either in $(H_0^{sp})^N(M)$ or in $(H^{sp})^N(M)$.

Let us prove (3.9).

Due to the definition of the norms we can suppose $N = 1$, $M = \mathbf{R}^n$ (or $M = \mathbf{R}^{n+}$) and $\text{supp } v_x \subset U$ for all $v_x I \in \Delta_x$ and a certain compact U .

Let $B^s = A^s$, $B^s = \tilde{A}_+^s$ or $B^s = \tilde{A}_-^s$ for the cases of the spaces $H^{sp}(\mathbf{R}^n)$ ($M = \mathbf{R}^n$), $H_0^{sp}(\mathbf{R}^{n+})$ or $H^{sp}(\mathbf{R}^{n+})(M = \mathbf{R}^{n+})$, respectively; due to Lemma 3.3 and isomorphical properties of B^s (cf. § 3.1) we easily get

$$\|v_x J\|_{sp} = C \|B^s v_x B^{-s}\| = C \|v_x J\|_p = C \|v_x J\|_p = C \sup_{\xi} |v_x(\xi)| = C,$$

where C depends only on $B^{\pm s}$.

Let now M' be another r -smooth n -dimensional (not necessarily compact) manifold with or without boundary; suppose there exists some r -diffeomorphism

$$\beta(t) : U_x \rightarrow U_y, \quad \beta(x) = y, \quad x \in M, y \in M'$$

of neighborhoods of the points x and y .

The operator

$$(3.10) \quad \beta_* \varphi(t) = \begin{cases} \varphi(\beta(t)), & t \in U_x, \\ 0, & t \notin U_x \end{cases}$$

is bounded

$$\beta_* \in \mathcal{L}((H_0^{sp})^N(M'), (H_0^{sp})^N(M)) \cap \mathcal{L}((H^{sp})^N(M'), (H^{sp})^N(M))$$

and its restrictions on $(H_0^{sp})^N(U_y)$ and on $(H^{sp})^N(U_y)$ are isomorphisms (β_* and its inverse β_*^{-1} are obviously bounded in $(H_0^{sp})^N(U_y)$ and $(H^{sp})^N(U_y)$ for $s =$ integer; for $s \neq$ integer their boundedness follows from interpolation Theorem 1.11).

Similarly to Δ_x ($x \in M$; cf. (3.8)) the localizing class Δ_y ($y \in M'$) is defined.

The operators $A \in \mathcal{L}_{sp}^N(M)$ and $B \in \mathcal{L}_{sp}^N(M')$ are called $(\Delta_x, \beta, \Delta_y)$ -equivalent (or quasiequivalent; cf. [6]), written $A \xrightarrow{\sim} \beta \xleftarrow{\sim} B$, if there exist two neighborhoods $U_x \subset M$, $U_y \subset M'$ and a diffeomorphism $\beta : U_x \rightarrow U_y$, such that

$$y = \beta(x), \quad \beta_*^{-1} A \beta_* \xrightarrow{\sim} B.$$

All properties of quasiequivalence listed in [6], page 577 (with exception of the property b)) are valid in the considered case as well.

With the help of Theorem 3.4 we easily prove the following.

THEOREM 3.5. *Let $A \in \mathcal{L}_{sp}^N(M)$, $B \in \mathcal{L}_{sp}^N(M')$ and*

$$A \xrightarrow{\sim} \beta \xleftarrow{\sim} B;$$

the operator A has a left (right) Δ_x -regularizer if and only if B has a left (right) Δ_y -regularizer.

In the case $s = 0$ we can add to Theorem 3.4 the following.

LEMMA 3.6. *If the operator $A \in \mathcal{L}(L_p^N(M)) \equiv \mathcal{L}_{0p}^N(M)$ has a left (right) Δ_x -regularizer, it is left (right) Δ_x -invertible.*

Proof. Let, for definiteness, A has a left Δ_x -regularizer

$$RAv_x I = v_x I + T, \quad T \in \mathfrak{S}(L_p^N(M)).$$

Since

$$\inf_{v \in \Delta_x} \|v\varphi\|_p = 0$$

for any $\varphi \in L_p^N(M)$, there exists such $v_0 I \in \Delta_x$ that

$$(3.11) \quad \|Tv_0 I\|_p < 1;$$

let $\tilde{v}_x I \in \Delta_x$ be such that

$$\tilde{v}_x v_0 = v_x \tilde{v}_x = \tilde{v}_x;$$

then

$$RA\tilde{v}_x I = (I + Tv_0)\tilde{v}_x I$$

and $I + Tv_0$ is invertible (cf. (3.11)); therefore

$$(I + Tv_0)^{-1}RA\tilde{v}_x I = \tilde{v}_x I$$

and A is left Δ_x -invertible. □

LEMMA 3.7. *Let $A \in \mathcal{L}(L_p^N(\mathbf{R}^n))$ (or $A \in \mathcal{L}(L_p^N(\mathbf{R}^{n+}))$) and*

$$V_\lambda A = AV_\lambda, \quad V_\lambda \varphi(t) = \varphi(\lambda t) \quad (\lambda > 0).$$

The operator A has a left (has a right) Δ_0 -regularizer if and only if A is normally solvable and $\dim \text{Ker } A = 0$ (is normally solvable and $\dim \text{Coker } A = 0$, respectively).

In particular A has a Δ_0 -regularizer if and only if A is the invertible operator.

Proof. Let A has a left Δ_0 -regularizer; then A is left Δ_0 -invertible (cf. Lemma 3.6)

$$(3.12) \quad RA v_0 I = v_0 I;$$

we prove now that

$$(3.13) \quad \inf_{\|\varphi\|_p=1} \|A\varphi\|_p > 0,$$

which is equivalent to the normal solvability and $\dim \text{Ker } A = 0$ (cf. [5]).

Let (3.13) does not hold: there exists a sequence $\{\varphi_j\}_{j=1}^\infty$ such that

$$(3.14) \quad \|\varphi_j\|_p = 1, \quad \lim_{j \rightarrow \infty} \|A\varphi_j\|_p = 0;$$

due to (3.12)

$$(3.15) \quad \begin{aligned} 1 &= \lim_{\lambda \rightarrow 0} \|v_\lambda \varphi_j\|_p = \lim_{\lambda \rightarrow 0} \|V_\lambda R V_{1/\lambda} A v_\lambda \varphi_j\|_p \leq \\ &\leq \|R\|_p [\|A \varphi_j\|_p + \|A\|_{p,p} \lim_{\lambda \rightarrow 0} \|v_\lambda \varphi_j - \varphi_j\|_p] = \|R\|_p \|A \varphi_j\|_p, \end{aligned}$$

where

$$v_\lambda(t) = v_0(\lambda t) = V_\lambda v_0(t).$$

Due to (3.14) the inequality (3.15) is a contradiction; thus (3.13) holds.

If A has a right Δ_0 -regularizer the conjugate operator A^* will have a left Δ_0 -regularizer and the result follows from duality (A is normally solvable and $\dim \text{Coker } A = 0$ if and only if A^* is normally solvable and $\dim \text{Ker } A^* = 0$).

A will be normally solvable and $\dim \text{Ker } A = \dim \text{Coker } A = 0$ provided A has both (left and right) Δ_0 -regularizers; therefore A will be invertible. \square

4. SINGULAR INTEGRAL OPERATORS ON A COMPACT MANIFOLD

1°. DEFINITIONS AND SIMPLEST PROPERTIES. Let M be a compact n -dimensional r -smooth manifold with the boundary $\partial M \neq \emptyset$; $\{u_j\}_{j=1}^l$ be a covering of M , $\bigcup_{j=1}^l u_j := M \cup \partial M$, $\bigcup_{j=k+1}^l U_j \supset \partial M$; $\beta_j: u_j \rightarrow u_j^0$ be homeomorphisms on compact domains $u_1^0, \dots, u_k^0 \subset \mathbf{R}^n$, $u_{k+1}^0, \dots, u_n^0 \subset \mathbf{R}^{n+}$.

The operator $A \in \mathcal{L}_{sp}^N(M)$, $|s| \leq r$, $1 < p < \infty$ (cf. (3.7)) is called the *singular integral operator* provided (cf. § 3.2°):

- (i) $AgI - gA \in \mathfrak{S}_{sp}^N(M)$ for all $g \in C'(M)$;
- (ii) $A \stackrel{x}{\sim} \beta_j \stackrel{\xi}{\sim} W_{a_x}^0$ for $x \notin \partial M$, $x \in U_j \cap M$ ($y \in \beta_j(x)$, $a_x(\xi) \in (Hm_p)^{N-N}(\mathbf{R}^n)$);
- (iii) $A \stackrel{x}{\sim} \beta_j \stackrel{\xi}{\sim} W_{a_x}^1$ for $x \in \partial M \cap U_j$ ($y = \beta_j(x) = (0, y_2, \dots, y_n)$, $a_x(\xi) \in (Hm_p)^{N-N}(\mathbf{R}^N)$).

$a_x(\xi)$ ($x \in M \cup \partial M \stackrel{\text{def}}{=} \bar{M}$) is called the *symbol* of the operator A .

LEMMA 4.1. *The symbol $a_x(\xi) \in (Hm_p)^{N-N}(\mathbf{R}^n)$ ($x \in \bar{M}$) of the singular integral operator $A \in \mathcal{L}_{sp}^N(M)$ is uniquely defined.*

Proof. We have to prove that if for a fixed $x \in \bar{M}$

$$(4.1) \quad A \stackrel{x}{\sim} \beta_j \stackrel{\xi}{\sim} W_b^k, \quad A \stackrel{x}{\sim} \beta_j \stackrel{\xi}{\sim} W_d^k,$$

where $b, d \in Hm_p(\mathbf{R}^n)$ and $k = 0$, $k = 1$ for $x \notin \partial M$, $x \in \partial M$, respectively, then $b(\xi) \equiv d(\xi)$; this clearly suffices.

Let first $x \in \partial M$ (hence $k = 1$ in (4.1)); from (4.1) we get

$$W_{b-d}^1 = W_b^1 - W_d^1 \xrightarrow{d} 0 \quad (y = \beta_j(x));$$

hence (cf. Definition in § 3.2°) for any $\varepsilon > 0$ there exist an operator $T_\varepsilon \in \mathfrak{S}_{sp}(\mathbf{R}^{n+})$ and a function $v_0(t) \in C_0^\infty(\mathbf{R}^n)$, $v_0(t) \equiv 1$ in some neighborhood of $y \in \mathbf{R}^{n+}$ such that

$$\|v_0 W_g^1 + T_\varepsilon\|_{sp} < \varepsilon \quad (g = b - d);$$

due to the isomorphism properties of Λ_\pm^s , and Lemmas 3.2 and 3.3 we obtain

$$(4.2) \quad \|v_0 W_{\hat{g}_s}^1 + T\|_p = \|\Lambda_-^s v_0 \Lambda_-^{-s} \Lambda_-^s W_g^1 \Lambda_+^{-s} + \Lambda_-^s T_\varepsilon \Lambda_+^{-s}\|_p = \|v_0 W_g^1 + T_\varepsilon\|_{sp} < \varepsilon,$$

where $T \in \mathfrak{S}(L_p^N(\mathbf{R}^{n+}))$ and

$$\hat{g}_s(\xi) = \left(\frac{i\xi_1 + |\xi'| + 1}{i\xi_1 - |\xi'| - 1} \right)^s g(\xi);$$

due to the compactness of $\text{supp } v_0$ we conclude (cf. (3.3) and Theorem 1.12)

$$v_0 W_{(\hat{g}_s - g \cdot g_s)}^1 \in \mathfrak{S}(L_p^N(\mathbf{R}^{n+})),$$

since

$$\lim_{|\xi| \rightarrow \infty} |\hat{g}_s(\xi) - g(\xi)g_s(\xi)| \equiv 0;$$

(4.1) yields then

$$\|v_0 W_{gg_s}^1\|_p < \varepsilon$$

and due to (1.14)

$$(4.3) \quad \sup_{\xi} |g(\xi)g_s(\xi)| \leq \|g W_{gg_s}^1\|_p = \|\chi W_{gg_s}^1\|_p \leq \|v_0 W_{gg_s}^1\|_p < \varepsilon,$$

where $\chi(\xi)$ is the characteristic function of the set $\{\xi \in \mathbf{R}^n : v_0(\xi) = 1\}$ (therefore $\chi v_0 = \chi$); from (4.3) immediately follows $b(\xi) \equiv d(\xi)$.

The case $x \notin \partial M$ ($k = 0$ in (4.1)) is completely similar. □

LEMMA 4.2. *The symbol $a_x(\xi)$ of the singular integral operator $A \in \mathcal{L}_{sp}^N(M)$ is a continuous function of $x \in \partial M$.*

Proof. Let $A \in \mathcal{L}_{sp}^N(M)$; by the definition of equivalence (cf. § 3.2°)

$$A \xrightarrow{x} \beta_j \xrightarrow{y} W_{a_x}^1 \quad (y = \beta_j(x)),$$

for any $\varepsilon > 0$ there exists $v_\varepsilon I \in A_y$ (cf. (3.8)) such that

$$\|v_\varepsilon[\beta_j^{-1}A\beta_j - W_{a_x}^1]\|_{sp} < \varepsilon;$$

let $x, z \in U_j$, $\beta_j(x) \in U_\varepsilon = \{\xi \in \mathbf{R}^{n+} : v_\varepsilon(\xi) := 1\}$; if $\tilde{v}_\varepsilon I \in A_{\beta_j(z)}$ is such that $\text{supp } \tilde{v}_\varepsilon \subset U_\varepsilon$ and

$$\|\tilde{v}_\varepsilon[\beta_j^{-1}A\beta_j - W_{a_z}^1]\|_{sp} < \varepsilon,$$

then

$$\begin{aligned} \|\tilde{v}_\varepsilon[W_{a_z}^1 - W_{a_x}^1]\|_{sp} &\leq C_1 \|\tilde{v}_\varepsilon v_\varepsilon[\beta_j^{-1}AB\beta_j - W_{a_x}^1]\|_{sp} + \\ &+ C_1 \|\tilde{v}_\varepsilon[\beta_j^{-1}A\beta_j - W_{a_z}^1]\|_{sp} < C_1(1 + \|v_\varepsilon\|_{sp}) \varepsilon, \end{aligned}$$

where C_1 depends only on s and p ; similarly to (4.2) – (4.3) we obtain

$$(4.4) \quad \sup_{\xi} |[a_z(\xi) - a_x(\xi)]g_s(\xi)| < C_1(1 + \|v_\varepsilon\|_{sp}) \varepsilon;$$

due to (3.9), from (4.4) it follows

$$\lim_{\substack{z \rightarrow x \\ z, x \in \partial M}} \sup_{\xi} |a_z(\xi) - a_x(\xi)| = 0. \quad \blacksquare$$

REMARK 4.3. Similarly to Lemma 3.2 one can prove that the symbol $a_x(\xi)$ is a continuous function of $x \in M \setminus \partial M$ as well.

REMARK 4.4. If $a_x(\xi) \in (Hm_p)^{N \times N}(\mathbf{R}^n)$ is the symbol of the singular integral operator $A \in \mathcal{L}_{sp}^N(M)$ and $\inf_{|\theta'|=1} |\det a_x(\theta)| > 0$ for all $x \in \partial M$, the numbers

$$\delta_j(a_x) := \frac{\ln \lambda_j(a_x)}{2\pi}, \quad \frac{1}{p} - 1 - s < \operatorname{Re} \delta_j(a_x) \leq \frac{1}{p} - s$$

$$(j = 1, 2, \dots, N, 1 < p < \infty)$$

can be defined (cf. § 3.1'), where $\lambda_1(a_x), \dots, \lambda_N(a_x)$ are the eigenvalues of the matrix $a_x^{-1}(-1, 0, \dots, 0)a_x(+1, 0, \dots, 0)$ (with regard of their multiplicities); *partial* (p, s)-*indices* $\varkappa_N(\theta', x) \leq \dots \leq \varkappa_1(\theta', x)$ ($\theta' \in S^{n-2}$, $x \in \partial M$) are also defined as in § 2.1'.

In the scalar case $N = 1$ all numbers $\delta_j(a_x)$ and $\varkappa(\theta', x) \equiv \varkappa_1(\theta', x)$ are continuous functions of $x \in \partial M$ (since $a_x(\xi)$ is continuous with respect to $x \in \partial M$) and therefore $\varkappa(\theta', x) \equiv \text{const.}$ (for $n > 2$), $\varkappa(\theta', x) \equiv \varkappa(\pm 1)$ (for $n = 2$).

REMARK 4.5. The above given definition of the singular integral operator (with slight variations) is well-known; in [6], for example, the condition (i) for the operator $A \in \mathcal{L}(L_p^N(M))$ is replaced by: (i') $\chi_1 A \chi_2$ is compact for all characteristic functions χ_1 and χ_2 with $\text{supp } \chi_1 \cap \text{supp } \chi_2 = \emptyset$.

Conditions (i) and (i') are equivalent (cf. Seeley's remark in Mathematical Reviews 31, # 3876).

2°. EXAMPLE. Let $M \subset \mathbf{R}^n$ be a compact domain with m -smooth ($m \geq 2$) boundary ∂M , let r be as in Theorem 1.1 and $|s| < l \leq m$.

Suppose

$$(4.5) \quad D_\xi^k \Omega(\xi, \theta) \in (H^{r2})^{N \times N}(M, S^{n-1}), \quad |k|_1 \leq l, \quad \int_{S^{n-1}} \Omega(\xi, \theta) d\theta \equiv 0$$

and for $\varepsilon > 0$ there exists a function

$$(4.6) \quad \begin{aligned} \Omega_\varepsilon(\xi, \theta) &= \sum_{j=1}^q \Omega_{j1}(\xi) \Omega_{j2}(\theta), \\ \int_{S^{n-2}} \Omega_{j2}(\theta) d\theta &= 0, \quad \Omega_{j1} \in (C')^{N \times N}(M), \quad \Omega_{j2} \in (H^{r2})^{N \times N}(S^{n-1}), \end{aligned}$$

such that

$$(4.7) \quad \|\Omega - \Omega_\varepsilon\|_{l, r} = \sum_{|k|_1 \leq l} \max_{\xi} \|D_\xi^k [\Omega(\xi, \cdot) - \Omega_\varepsilon(\xi, \cdot)]\|_{H^{r2}(S^{n-1})} < \varepsilon.$$

Consider the operator

$$A_M \varphi(\xi) = \int_M \frac{\Omega(\xi, \xi - \eta)}{|\xi - \eta|^n} \varphi(\eta) d\eta;$$

due to Theorem 1.1 $A_M \in \mathcal{L}_{sp}^N(M)$ (cf. (3.7)).

The operator

$$T = A_M g I - g A_M \quad (g \in C^m(M))$$

has a weak singular kernel and therefore is compact on $L_p^N(M)$; due to Theorem 1.11 (cf. (3.7)) $T \in \mathfrak{S}_{sp}^N(M)$.

Let $\beta_x : u_x \rightarrow u_0$ be some homeomorphism of the neighborhoods $u_x \subset M$, $u_0 \subset M_x$, where $\beta_x(x) = 0$ and

$$(4.8) \quad M_x = \begin{cases} \mathbf{R}^{n+}, & \text{if } x \in \partial M \\ \mathbf{R}^n, & \text{if } x \in M \setminus \partial M; \end{cases}$$

let J_x be the Jacobian of $\beta_x(t)$ at the point x (if $x \in M \cup \partial M$ we can suppose $\beta_x(t) \equiv t - x$ and hence $J_x \equiv 1$).

Let now (cf. (4.8))

$$A_x \psi(t) = \int_{M_x} \frac{\Omega_x(x, t - \tau)}{|t - \tau|^n} \psi(\tau) d\tau, \quad \Omega_x(x, \xi) \equiv \Omega(x, J_x^{-1} \xi);$$

in virtue of Theorem 1.1 $A_x \in \mathcal{L}_{sp}^N(M_x)$.

The equivalence

$$(4.9) \quad A_M \xrightarrow{x} \beta_x \xrightarrow{y} A_x \quad (x \in M, y = \beta_x(x))$$

is valid.

Proof. We prove first the equivalence (cf. (3.8))

$$(4.10) \quad A_M \xrightarrow{x} \tilde{A}_x,$$

where

$$\tilde{A}_x \varphi(\xi) = \int_M \frac{\Omega(x, \xi - \eta)}{|\xi - \eta|^n} \varphi(\eta) d\eta.$$

Suppose $\Omega = \Omega_\varepsilon$ (cf. (4.5)), $x \in M \setminus \partial M$ and $\text{supp } v_x \subset M$ ($v_x I \in \mathcal{A}_x$); then in virtue of Theorem 1.1 and Lemma 3.3

$$\begin{aligned} \|v_x^2 [A_M - \tilde{A}_x]\|_{sp} &= \|v_x [A_M - \tilde{A}_x] v_x\|_{sp} \leq \\ &\leq \sum_{j=1}^q \|v_x \tilde{\Omega}_{j1} A_{j2} v_x\|_{sp} = \sum_{j=1}^q \|A^s v_x \Omega_{j1} A_{j2} v_x A^{-s}\|_p \leq \\ &\leq \sum_{j=1}^q \|A^s v_k \tilde{\Omega}_{j1} A^{-s}\|_p \|A^s A_{j2} A^{-s}\|_p \|A^s v_k A^{-s}\|_p \leq \sum_{j=1}^q \|v_k \tilde{\Omega}_{j1} I\|_p \|A_{j2}\|_{sp} \|v_k I\|_p \leq \\ &\leq \sum_{j=1}^q \sup_{\xi \in M} |v_k(\xi)[\Omega_{j1}(\xi) - \Omega_{j1}(x)]| \|A_{j2}\|_{sp} \leq \\ &\leq \sum_{j=1}^q \|\Omega_{j2}\|_{l,r} \sup |v_k(\xi)[\Omega_{j1}(\xi) - \Omega_{j1}(x)]| \end{aligned}$$

where $\tilde{\Omega}_{j1}(\xi) := \Omega_{j1}(\xi) - \Omega_{j1}(x)$,

$$A_{j2} \varphi(\xi) = \int_M \frac{\Omega_{j2}(\xi - \eta)}{|\xi - \eta|^n} \varphi(\eta) d\eta$$

and $\|\cdot\|_{l,r}$ is defined by (4.7).

Thus

$$\inf_{v_k I \in \mathcal{A}_x} \|v_k [A_M - A_x I]\|_{sp} = 0$$

and (4.10) is proved for $x \in M \setminus \partial M$, $\Omega = \Omega_\varepsilon$.

Simple continuity arguments prove (4.10) for all $\Omega(\xi, \theta)$.

For proving (4.10) we need to consider only the case $x \in \partial M$, $\Omega = \Omega_\epsilon$.

Let $\text{supp } v_x \subset u_x$ ($v_x I \in A_x$; cf. (3.8)), $v_x^0 = \beta_{x^*}^{-1} v_x$, $\Omega_{j1}^0 = \beta_{x^*}^{-1} \tilde{\Omega}_{j1}$ ($\tilde{\Omega}_{j1}(\xi) = \Omega_{j1}(\xi) - \Omega_{j1}(x)$) and $A_{j2}^0 = \beta_{x^*}^{-1} A_{j2} \beta_{x^*}$ (cf. (3.10)); applying Theorem 1.1, Lemma 3.3 and inequality (3.9) we get

$$\begin{aligned} \|v_x^2 [A_M - \tilde{A}_x]\|_{sp} &\leq C_1 \sum_{j=1}^q \|v_x^0 \Omega_{j1}^0 A_{j2}^0 v_x^0\|_{sp} \leq C_1 \sum_{j=1}^q \|[\tilde{A}_-^s v_x^0 \Omega_{j1}^0 A_{j2}^0 v_k^0 \tilde{A}_+^{-s}]\|_p \leq \\ &\leq C_1 \sum_{j=1}^q \|[\tilde{A}_-^s v_x^0 \Omega_{j1}^0 \tilde{A}_-^{-s}]\|_p \|[\tilde{A}_-^s A_{j2}^0 \tilde{A}_+^{-s}]\|_p \|[\tilde{A}_+^s v_x^0 A_+^{-s}]\|_p = \\ &= C_1 \sum_{j=1}^q \sup |v_x(\xi)| [\Omega_{j1}(\xi) - \Omega_{j1}(x)] \|\Omega_{j2}\|_{l_r}; \end{aligned}$$

hence

$$\inf_{v_x I \in A_x} \|v_x [A_M - \tilde{A}_x]\|_{sp} = 0$$

and (4.10) is proved.

Next the equivalence

$$(4.11) \quad \tilde{A}_x \stackrel{x}{\sim} \beta_x \stackrel{y}{\sim} A_x \quad (y = \beta(x))$$

will be proved, which together with (4.10) yields (4.9).

It suffices to consider $\Omega(x, \xi) \in C^\infty(S^{n-1})$ for all $x \in M$ (otherwise we can approximate Ω and use the continuity property of the equivalence (4.11)); rewrite (4.11) as (cf. § 3.2)

$$\beta_{x^*}^{-1} \tilde{A}_x \beta_{x^*} \stackrel{y}{\sim} A_x;$$

in [6], Chapter I, § 4 was proved that

$$(4.12) \quad \beta_{x^*}^{-1} \tilde{A}_x \beta_{x^*} = A_x + B + T,$$

where $T \in \mathfrak{S}(L_p^N(M_x))$,

$$B\psi(t) = \int_M \frac{\Omega_0(t, t - \tau)\psi(\tau) d\tau}{|\tau - t|^n},$$

$$\Omega_0(\beta_x(x), \xi) \equiv 0, \quad D_t^k \Omega_0(t, \xi) \in (C^\infty)^{N \times N}(S^{n-1}), \quad |k|_1 \leq m.$$

Clearly $B, T \in \mathcal{L}_{lp}^N(M_x)$ and in virtue of Theorem 1.11 $T \in \mathfrak{S}_{sp}^N(M_x)$. Similarly to (4.10) we get $B \stackrel{y}{\sim} 0$ ($y = \beta_x(x)$) and, therefore, (4.12) yields (4.11). \blacksquare

3°. STATEMENT OF THEOREMS.

THEOREM 4.6. *Let M be a compact n -dimensional r -smooth manifold with the boundary $\partial M \neq \emptyset$; $A \in \mathcal{L}_{sp}^N(M)$ be a singular integral operator with the symbol $a_x(\zeta) \in (HC^{m+2})^{N \times N}(\mathbf{R}^n)$ ($x \in M \cup \partial M$, $m > n/2$, $-\infty < s < \infty$, $1 < p < \infty$) which is elliptic $\inf_{\substack{x \in M \\ |\theta| = 1}} |a_x(\theta)| > 0$.*

The operator $A \in \mathcal{L}_{sp}^N(M)$ is Fredholm if and only if (cf. Remark 4.4)

$$(4.13) \quad \delta_j(a_x) \neq \frac{1}{p} - s \quad \text{for all } j = 1, 2, \dots, N$$

and all partial (p, s) -indices disappear

$$(4.14) \quad \varkappa_1(\theta', x) \equiv \dots \equiv \varkappa_N(\theta', x) \equiv 0 \quad (\theta' \in S^{n-2}, x \in M).$$

THEOREM 4.7. *Let all preliminaries of Theorem 4.6 together with (4.13) held.*

If $\varkappa_j(\theta', x) \geq 0$ ($j = 1, 2, \dots, N$; $\theta' \in S^{n-2}$; $x \in M$) but (4.14) does not hold the operator $A \in \mathcal{L}_{sp}^N(M)$ has a left regularizer and $\dim \text{Coker } A = \infty$.

If $\varkappa_j(\theta', x) \leq 0$ ($j = 1, 2, \dots, N$; $\theta' \in S^{n-2}$; $x \in M$) but (4.14) does not hold, the operator $A \in \mathcal{L}_{sp}^N(M)$ has a right regularizer and $\dim \text{Ker } A = \infty$.

THEOREM 4.8. *Let M be a compact n -dimensional r -smooth manifold with the boundary $\partial M \neq \emptyset$; $A \in \mathcal{L}_{sp}^N(M)$ be a singular integral operator with the symbol $a_x(\zeta) \in (HC^{m+2})^{N \times N}(\mathbf{R}^n)$ ($x \in M \cup \partial M$, $m > n/2$, $-\infty < s < \infty$, $1 < p < \infty$).*

If $\inf |\det a_x(\theta)| = 0$ ($x \in M \cup \partial M$, $\theta \in S^{n-1}$), the operator $A \in \mathcal{L}_{sp}^N(M)$ has no left and no right regularizer.

4°. PROOF OF THEOREM 4.6. Due to the definition of singular integral operators $A \in \mathcal{L}_{sp}^N(M)$ and to Theorem 3.5, A has a regularizer (i.e. A is a Fredholm operator) if and only if $W_{a_x}^0 \in \mathcal{L}_{sp}^N(\mathbf{R}^n)$ for all $x \in M \setminus \partial M$ and $W_{a_x}^1 \in \mathcal{L}_{sp}^N(\mathbf{R}^{n+})$ for all $x \in \partial M$ have Δ_y -regularizers (cf. (3.8); here $y = \beta_j(x)$ for $x \in u_j$, $\bigcup_{j=1}^l u_j = M \cup \partial M$; cf. § 4.1°).

We prove now that $W_{a_x}^0 \in \mathcal{L}_{sp}^N(\mathbf{R}^n)$ ($x \in M \setminus \partial M$) and $W_{a_x}^1 \in \mathcal{L}_{sp}^N(\mathbf{R}^{n+})$ ($x \in \partial M$) have Δ_y -regularizers if and only if $W_{a_x}^0 \in \mathcal{L}_{sp}^N(\mathbf{R}^n) = \mathcal{L}(L_p^N(\mathbf{R}^n))$ and $W_{a_x g_s}^1 \in \mathcal{L}(L_p^N(\mathbf{R}^{n+}))$ have Δ_0 -regularizers respectively, ($g_s(\zeta)$ is defined by (3.3)).

Let $W_{a_x}^0 \in \mathcal{L}_{sp}^N(\mathbf{R}^n)$ has a left Δ_0 -regularizer:

$$(4.15) \quad RW_{a_x}^0 v_y I = v_y I + T, \quad v_y I \in \Delta_y, \quad T \in \mathfrak{S}_{sp}^N(\mathbf{R}^n);$$

then (cf. § 3.1°)

$$V_y A^s R A^{-s} V_{-y} (V_y A^s W_{a_x}^0 A^{-s} V_{-y}) V_y A^s a_0 A^{-s} V_{-y} = V_y A^s V_0 A^{-s} V_{-y} + V_y A^s T A^{-s} V_{-y},$$

where

$$V_{\pm y}\varphi(t) = \varphi(t \mp y);$$

obviously

$$V_y W_{a_x}^0 V_{-y} = W_{a_x}^0, \quad V_y a_y V_{-y} \in \Delta_0$$

and using Lemmas 3.1, 3.3 we get

$$(4.16) \quad R_0 W_{a_x}^0 v_0 I = v_0 I + T_0;$$

$R_0 = V_y A^s R A^{-s} V_{-y} \in \mathcal{L}_p^N(\mathbf{R}^n)$, $T_0 \in \mathfrak{S}(L_p^N(\mathbf{R}^n))$; hence $W_{a_x}^0 \in \mathcal{L}(L_p^N(\mathbf{R}^n))$ has a left Δ_0 -regularizer.

Converting the argumentation from (4.16) we easily obtain (4.15).

Similarly, if $W_{a_x}^0 \in \mathcal{L}_{sp}^N(\mathbf{R}^n)$ has a right Δ_0 -regularizer, $W_{a_x}^0 \in \mathcal{L}(L_p^N(\mathbf{R}^n))$ will have a Δ_0 -regularizer and vice versa.

Let now $W_{a_x}^1 \in \mathcal{L}_{sp}^N(\mathbf{R}^n)$ has a left Δ -regularizer ($x \in \partial M$, $y = \beta_j(x)$),

$$(4.17) \quad RW_{a_x}^1 v_y I = v_y T + T, \quad v_y I \in \Delta_y, \quad T \in \mathfrak{S}((H_0^p)^N(\mathbf{R}^{n+}));$$

then (cf. § 3.1°)

$$R_0(V_y \tilde{A}_-^s W_{a_x}^1 \tilde{A}_+^{-s} V_{-y})(V_y \tilde{A}_+^s a_0 \tilde{A}_+^{-s} V_{-y}) = V_y \tilde{A}_+^s a_0 \tilde{A}_+^{-s} V_{-y} + T_0,$$

$$R_0 = V_y \tilde{A}_+^s R \tilde{A}_-^{-s} V_{-y} \in \mathcal{L}(L_p^N(\mathbf{R}^{n+})),$$

$$T_0 = V_y \tilde{A}_+^s T \tilde{A}_+^{-s} V_{-y} \in \mathfrak{S}(L_p^N(\mathbf{R}^{n+})),$$

since $x \in \partial M$, $y = \beta_j(x) = (0, y_2, \dots, y_n)$ and therefore

$$V_y W_{a_x}^1 V_{-y} = W_{a_x}^1, \quad V_y a_y V_{-y} \in \Delta_0$$

(if $y_1 \neq 0$, $V_{\pm y} \notin \mathcal{L}(L_p^N(\mathbf{R}^{n+}))$); using Lemmas 3.2 and 3.3 we get

$$(4.18) \quad R_0 W_{a_x}^1 v_0 I = v_0 I + T_1, \quad T_1 \in \mathfrak{S}(L_p^N(\mathbf{R}^{n+})).$$

Converting the argumentation from (4.18) we easily obtain (4.17).

Similarly is considered the case of a right Δ_y -regularizer of $W_{a_x}^1$.

Summarizing we conclude: $A \in \mathcal{L}_{sp}^N(M)$ is a Fredholm operator if and only if $W_{a_x}^0 \in \mathcal{L}(L_p^N(\mathbf{R}^n))$ have Δ_0 -regularizers for all $x \in M \setminus \partial M$ and $W_{a_x g_s}^1 \in \mathcal{L}(L_p^N(\mathbf{R}^{n+}))$ have Δ_0 -regularizers for all $x \in \partial M$.

The proof of the theorem is completed now with the help of Lemma 3.7 and Theorem 2.7. □

5°. PROOFS OF THEOREMS 4.7 AND 4.8. These theorems, similarly to Theorem 4.6, are simple consequences of Theorems 2.7 — 2.8 and Lemma 3.7 if we notice (cf. (4.15) — (4.18)):

- (i) if all $W_{a_x}^0 \in \mathcal{L}(L_p^N(\mathbf{R}^n))$ ($x \in M \setminus \partial M$) and all $W_{a_x s}^1 \in \mathcal{L}(L_p^N(\mathbf{R}^{n+}))$ have a left (have a right) Δ_0 -regularizer, A has a left (has a right) regularizer;
- (ii) if $W_{a_x}^0 \in \mathcal{L}(L_p^N(\mathbf{R}^n))$ ($x \in M \setminus \partial M$) or $W_{a_x}^1 \in \mathcal{L}(L_p^N(\mathbf{R}^{n+}))$ ($x \in \partial M$) is not a Fredholm operator for some $x \in M$, A will be not a Fredholm operator as well.

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ROLAND DUDUCHAVA
Institute of Mathematics,
Z. Rukhadze str. 1,
Tbilisi, 380093,
U.S.S.R.

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